

The new series with direct drive



For millturn and grinding applications or for 5-axis simultaneous machining

**DD** Series

> Direct Drive

2021

Main catalog

6.2021 | EN



## Swiss precision technology

Today, pL LEHMANN is still a family-owned and managed company in the hands the second generation and present in over 20 countries (see the back of this catalog).

The company is committed to typical Swiss values: ...

- Depth of manufacturing over 90% developed and manufactured in-house
- Product quality reliable, durable, safe
- High-tech Industry 4.0-compatible, ready to be automated
- Innovation in tune with the times, adaptable, trendsetting
- Sustainability long-term approach to business, environmentally conscious
- Basic values honest, correct, fair



\* Sales and service partners trained and equipped by pL (VAR – value added resellers or VAP - value added partners)

For more information see www.lehmann-rotary-tables.com

... and specialized in rotary tables for over 40 years:

1960	Founding - Contract manufacturing
1973	Conversion into a stock corporation
1974	Introduction of the first numerically controlled rotary tables (HUST)
1980	Construction of new factory building
1986	Development of the 400 series
1988	2nd generation joins the company's management
1997	Construction of new assembly building
2000	Development of the 800 series

Development of the 800 series (direct drive up to 10'000 rpm)
 2002 2nd generation assumes management

responsibility

2003 Development of the 700 series (direct drive up to 800 rpm)

Addition of office building
 Development of the 500 series
 Start of internationalization / lean production

2013 Development of the high-speed version of the 500 series

2016 Expansion of factory building

2017 Introduction of the 600 series and the start of AM-LOCK development

2019 Introduction of the 900 DD series up to 5'450 rpm and market launch of AM-LOCK, as well as the development and introduction of the AM-SHAFT construction shaft concept

#### Other pL products

**CNC Rotary Tables** classic



Main catalog - Series 500

Zero-point clamping system for 3-D printing



AM-LOCK

4

Whoever wishes to invest in tomorrow's way of production must consider the needs and opportunities available today



CNC rotary tables for economical manufacturing: pL LEHMANN offers tailor-made and efficient and solutions for almost any industry - and 10 years of experience in direct drives















Automobile & Mobility

Medical & dental

Micromechanical parts & watches

Aircraft & turbines

Machinery & tools

systems



pL rotary tables in use: on over 200 different machine brands and over 1,000 different machine models.

pL competence: Integration in all known CNC control systems (Fanuc, Siemens, Heidenhain, Haas, Winmax, Mitsubishi, Brother, Mazatrol ...), for new machines as well as for retrofits

up to 5'450 rpm

**High-speed DD** 

Extended travel in Z- and X-direction

More space

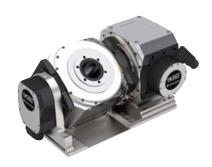


## **EA-Series**





## **T1-Series**



DD/DD



DD/PGD



## **Adaptability**

Multifunctional spindle system

### **Precision**

At the workpiece up to 2 µm / 100 mm

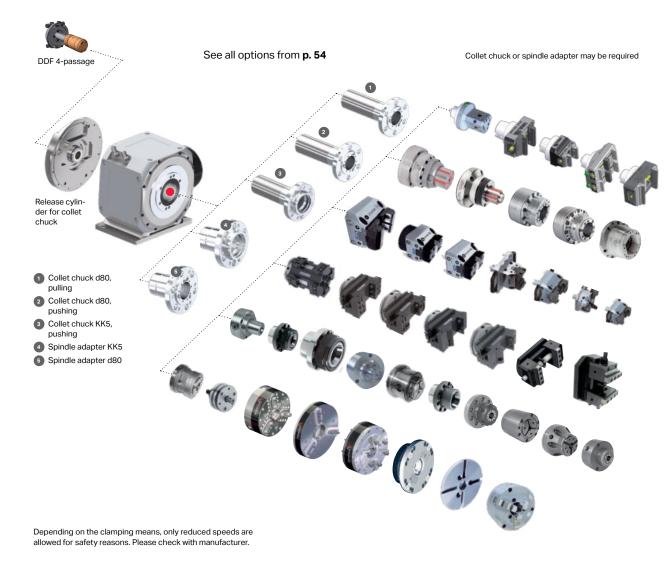
## **High duty time**

By default for ED40%, 10 min

Extremely wide assortment for workpiece clamping. Standardized interface in front and rear: Maximum universality



Tap or medium interface



































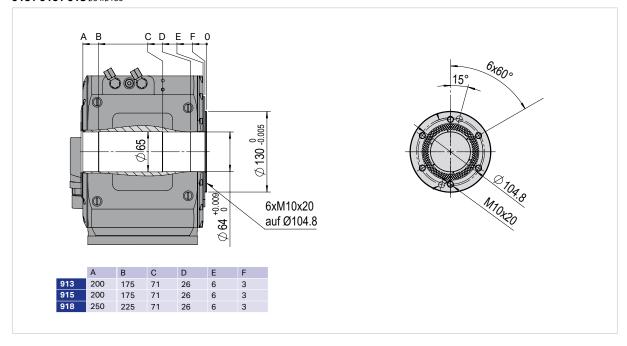




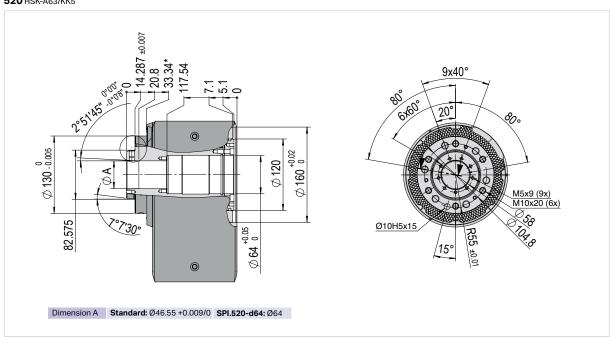


All spindle connection dimensions front and back for building your fixture. Applies to all variants, EA or T-type rotary table alike

#### Module size 913 / 915 / 918 ø64/ø130



## Module size 520 HSK-A63/KK5



Innovative CUBE-design based on 10 years of experience with DD technology: fully sealed, super-fast, safe, versatile and service-friendly - for Industry 4.0



NEW available with FANUC angular position measuring system – 100% FANUC DDR-compatible!

#### Transport and attachment holes

- Bolt holes for transport
- may be used for fixtures, tool monitoring, measuring probes

#### Angular position measuring system & temperature monitoring fully integrated

- RENISHAW angular position measuring system for SIEMENS, MITSUBISHI, YASKAWA and BISS
- FANUC measuring system, 100% compatible with FANUC DDR

#### Prepared for water cooling

For high speeds and/or long duty cycles (for more information see p. 24)

#### Universal spindle nose

- Large mounting Ø 130 mm (outside)
- Large through-bore Ø 64 mm

#### Innovative sealing system

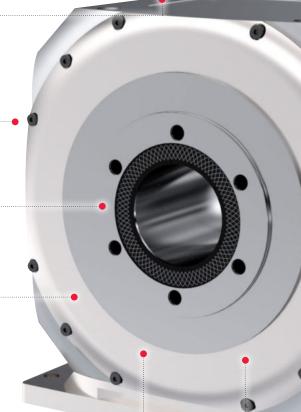
- 100% leaktight in accordance with IP67
- Front and rear labyrinth backed by lip seal with minimal friction loss
- Very high efficiency and minimal heat generation

#### Spindle bearing

- High-quality, preloaded spindle bearing at front and support bearing at rear
- Designed for very high rpm values
- Lifetime-lubricated

#### Spindle clamping with fail-safe function

- on large diameter
- energyless clamping
- large clamping diameter
- only 5 6 bar air pressure required
- Unique: emergency braking without damage in case of power failure







#### Rugged cast housing



### Mobile base plate

- Steel
- 3 sides accessible for mounting at all times
- Cable outlet direction selectable (also at a later date)

#### ■-iBox – for real Industry 4.0

Helps to increase productivity and availability, lower downtime and maintenance costs and permits quick troubleshooting and preventive maintenance.

#### Sensors for ...

- Speed
- Internal pressure
- Temperature
- Humidity
- Shock / impact
- Limit value exceeded with real-time stamp

#### Components

- Fast microprocessor
- 3D acceleration sensor shock sensor

#### Monitoring

Duty cycle limit – overload protection, prevents motor damage

#### Interfaces

- Bluetooth set parameters and read out data via smartphone and app
- Web server with Ethernet and RJ45 port display state/error on CNC
  - Input for current sensor

#### Prepared for options

- External WLAN or GSM module
- External, enhanced vibration sensor with additional DSP
- E-mail notification, e.g. of error messages



Never search for documents again – everything at hand at all times

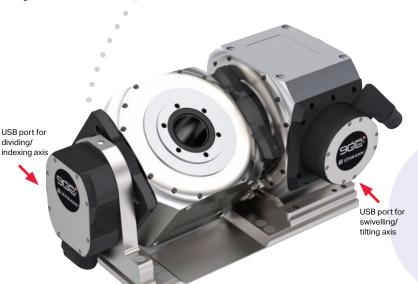
No Internet connection necessary!

#### The everyday life of a commissioning technician

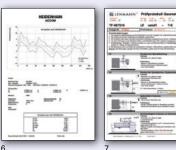
The information needed is missing: electrical schematics, drive data, parameter lists, commissioning instructions ... Commissioning must be interrupted, the search for data begins: paper? Internet? Passwords?. Time is passing. The deadline is approaching. The urgency of the situation means do the best possible with existing knowledge.

**Result:** It rotates, but functions only halfway, pL specifications cannot be met (rotational speed, cycle time, accuracy...)

**pL finding:** Investigations have shown that 70% of optimization cases can be attributed to poor or incorrect commissioning.







#### smart doc on the USB stick

- A mini USB stick is plugged into a USB slot (in the swiveling/tilting axis on T-type rotary tables)
- The following files have been saved on this USB stick:
   1 ADAT drive setup data for each system
  - 2 Appropriate parameter list for the provided CNC control system
  - 3 General operating manual / user's manual in German and English
  - 4 General commissioning manual in German and English with all diagrams
- 5 If necessary, machine-specific commissioning manual in German and English (e.g. for Fanuc)
- 6 Indexing accuracy report(s) to VDI/DGQ 3441 7 Geometry report
- 8 If necessary, special drawings from the customer
- The files are also available online in the pL-ERP (for Helpliner) as well as in the «full documentation» on the pL website (accessible to all pL representatives)
- All files at the current revision level version check not needed, risk of errors minimized



## Product documentation saved securely: The USB stick remains on the product

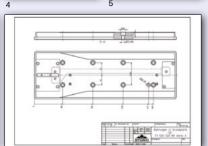


#### Your benefit

- Download no longer necessary extra work eliminated
- Password no longer necessary waiting for registration eliminated
- Internet no longer necessary problems with poor of no network connection eliminated
- No lost documents, no missing USB stick stick is always inserted, «loaded» and safety protected under the USB slot cover
- Everything needed is immediately available (appropriate for each rotary table) - tedious searching eliminated
- Emergency solution by technician no longer necessary - existing, often wrong (because out-of-date) data are no longer used









everything is still availab le on the website.





Very good accessibility, even with short tools

Y-mounting (transverse)

More space for workpiece and fixtures



**T1** 

**T1** 

max. 2'560 rpn

**T1** 

1'000 Nm

ø 356 mm

97 kg max. 1'300 rpm ø 285 mm 1'000 Nm 973978 ø 218 mm

76 kg

EA

max. 3'210 rpm

AGG, DDF,
RST, LOZ KAB, CNC, WMS

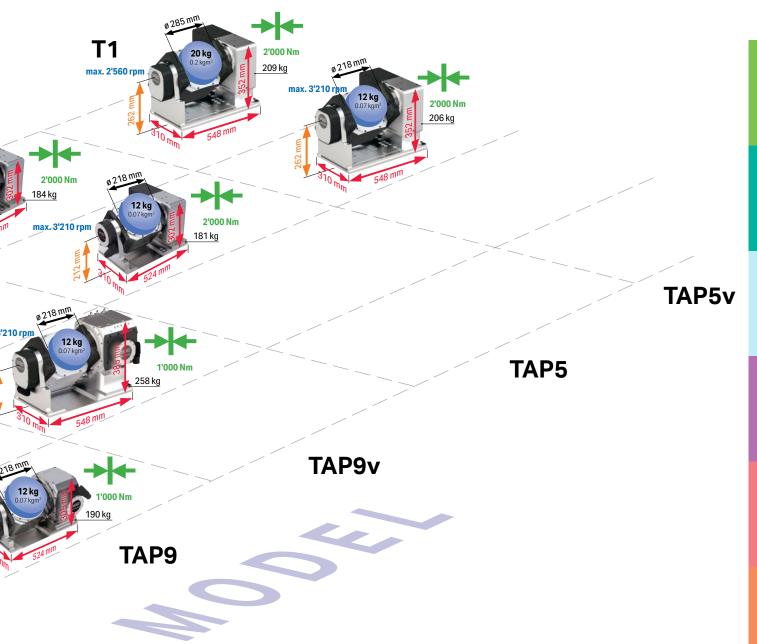
System & iBox

**□** LEHMANN®

79 kg max. 2'560 rpm

978

- For millturn applications (e.g. watch cases from bar stock)
- Modular concept in **Cube design**
- DD up to 5'450 rpm (without flux weakening function: max. 3'210 possible)
- Very compact
- For Siemens, Mitsubishi and Fanuc with Fanuc measuring system, 100%
   Fanuc DDT-compatible (other upon request)

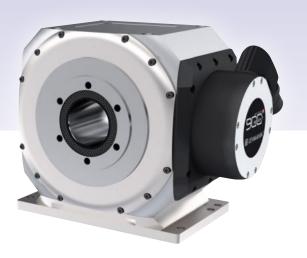


Weight data represent the standard load; higher weights possible, but require modification of rotational speed, acceleration and jerk limitation.

EA single-axis, single-spindle CNC rotary table
TAP two-axis rotary table, with supporting bearing
TAPv Two-axis rotary table, with support bearing,
low-profile version (vario)

Feed max.: without flux weakening

#### EA-913 DD / EA-915 DD





Clamping bridge system upon request

#### General technical data

				EA-913	EA-915	EA-918
Weight			kg	76	79	97
Spindle through-bore			mm		64	
Clamping torque at max. 5 bar air pressure		<b>X</b> ↑- <b>+</b> -	Nm		max. 800	
Spindle load	without support		kg	10	00	120
(max. permissible)	with support	- / <del>-</del>	, ky	20	00	240
Axial force (max. permissible)		<b>*</b>	kN		20	
Dull auttaunus	clamped	Nm	1,000		1,200	
Pull-out torque	unclamped	/x^	INIII	400 500		500
Moment of inertia	Standard load		Leans 2	0.07	0.2	0.5
Moment of Inertia	J max	Ų	kgm²	0.7	2	5
	Fanuc		±		4	
Positioning accuracy +/-	Siemens 1-head	果			11 (6*)	
(unloaded)	Siemens 2-head		arc sec	3 (2*)		
	Mitsubishi			11 (6*)		
Repeat accuracy +/- (unloaded)		$\oplus$	± arc sec		1	
Cycle time with standard load	90°			0.19	0.24	0.24
(without clamping)	180°		sec	0.24	0.3	0.3

<sup>\*</sup> Option: WMS.91x-GEN

#### Outgoing cable unit variants



Outgoing cable unit left

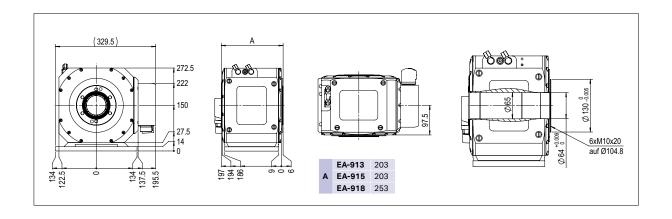


Outgoing cable unit top



Outgoing cable right

Can be easily converted by the customer at any time.



#### **Features**

- Angular position measuring system +/- 3 arc sec.
- Fail-safe clamping
- Leaktight IP 67
- Workpiece clamping system can be retrofitted with clamping cartridges



Motor data also applies to dividing/indexing axis on T-type rotary tables p. 16–19

Calculated, theoretical values; subject to change.

#### Wet-machining



Splash-water cooling - no cooling unit required (immersed in coolant, cooling emulsion max. 30 °C)

#### Dry machining

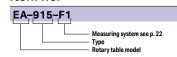




Water cooling - cooling unit required 4) (required if splash water cooling is not sufficient)

	Rotary table type	Motor	Peak current 3)	Max speed <sup>6)</sup> without flux weakening	Max speed <sup>6)</sup> with flux weakening <sup>2)</sup>	Peak torque	Intermittent torque	Continuous torque	Standstill torque
						ED5%	ED40%	ED1	100%
			[A]	[17	om]		[]	lm]	
beed	Type 913 <sup>1)</sup>	MOT.ET-A	70	2170	3030	67	38	26	20
00 V Standard speed	Type 915	мот.ет-в	67	1300	2070	117	70	48	37
200 V Stan	Type 918	MOT.ET-C	63	651	1120	234	147	101	77
2 High speed	Type 916 <sup>5)</sup>		50	888	4350	120	90	65	51
peeds	Type 913 <sup>1)</sup>	MOT.ET-A	70	3210	3210	67	38	26	20
dard s	Type 915	МОТ.ЕТ-В	67	2560	2770	117	70	48	37
400 V Standard	Type 918	MOT.ET-C	63	1300	1850	234	147	101	77
4 High speed	Type 916 <sup>5)</sup>		50	1780	5450	120	90	65	51

#### Item no.



<sup>&</sup>lt;sup>1)</sup> not available as swivelling/tilting axis for T1-91x915 TAP9 <sup>2)</sup> On Fanuc, a special servo and an additional module are needed for operation «with flux weakening» (does not have space in Robodrill cabinet); check with Fanuc

<sup>(</sup>does not have space in knobdriii cabinet; cneck with Fanuc
3 The servo booster must provide at least this peak current to achieve the values stated in the table
4 Recommended for use with a cooling unit (see p. 24):
- approx. 1'600 W rated cooling capacity and at least 1'300 W actual cooling capacity
- Coolant: water-like, non-corrosive

<sup>&</sup>lt;sup>5)</sup> Not yet available; upon request <sup>6)</sup> Applies to moment of inertia of standard load

#### T1-913915 TAP9 / T1-915915 TAP9



## Both axes with direct drive

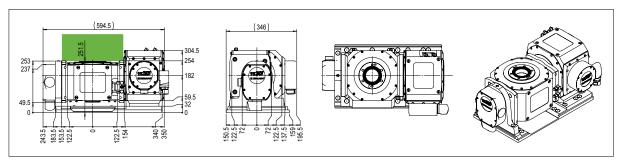
- Perm. spindle load up to 90 kg
- Maximum workpiece Ø 308 mm

#### General technical data

Drive data: see page 15

			T1-913915 TAP9	T1-913918 TAP9v
Weight (aluminum base plate)		kg	190 (166)	258
Spindle through-bore		mm	64	
Clamping torque	4th axis	Nm	max. 8	200
at max. 5 bar air pressure	5th axis	Nm	IIIAX. C	300
Spindle load (max. permissible)	-)	kg	40	90
Axial force (max. permissible)	<b>)</b> <del>/-</del>	kN	20	
D.:!!	clamped	Nm	1,00	0
Pull-out torque	unclamped	NM	400	)
Moment of inertia	Standard load	kgm²	0.07	7
woment of mertia	J max	Ngiii	0.7	
	4th axis Fanuc		4	
	5th axis Fanuc		4	
	4th axis Siemens 1-head		11 (6	5*)
Positioning accuracy +/-	5th axis Siemens 1-head	± arc sec	13 (9	)*)
(unloaded, -90 to +90°)	4th axis Siemens 2-head	± aic sec	3 (2*	*)
	5th axis Siemens 2-head		3 (2*	*)
	4th axis Mitsubishi		11 (6*)	
	5th axis Mitsubishi		13 (9	9*)
Repeat accuracy +/-	4th axis		1	
(unloaded)	5th axis	± arc sec	'	
	4th axis 90°		0.19	e
Cycle time with standard load	5th axis	000	0.48	0.46
without clamping)	4th axis	sec	0.24	4
(wanda dan ping)	5th axis		0.65	0.61

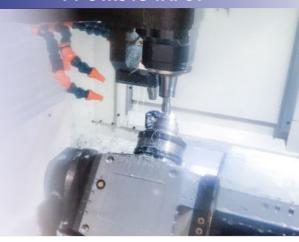
<sup>\*</sup> Option: WMS.91x-GEN





#### T1-913918 TAP9v / T1-915918 TAP9v





## Shorter machine travel for simultaneous machining

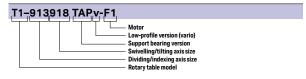
- Accelerated machining
- Higher accuracy at the workpiece

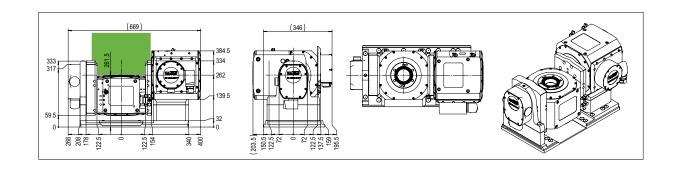
#### **Available combinations**

	Dividing/indexing axis motor*	Swivelling/tilting axis motor*	
T1-913915 TAP9	MOT.ET-A	MOT.ET-B	
T1-915915 TAP9	MOT.ET-B	MOT.ET-B	on request
T1-913918 TAP9v	MOT.ET-A	MOT.ET-C	
T1-915918 TAP9v	MOT.ET-B	MOT.ET-C	on request

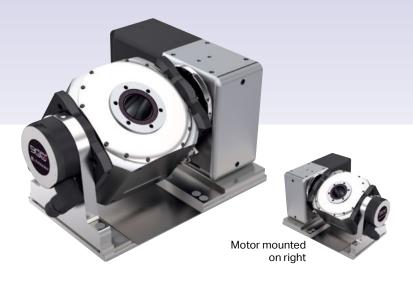
<sup>\*</sup> Motor data: see p. 15

#### Item no.





#### T1-913520 TAP5 / T1-915520 TAP5



# Dividing/indexing axis with direct drive Swivelling/tilting axis with rugged gear unit

- Perm. spindle load up to 90 kg
- Maximum workpiece Ø 400 mm

#### General technical data

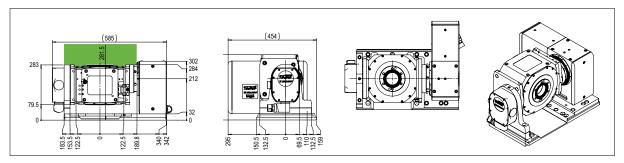
For drive data of dividing/indexing axis (rotation) see p. 15, for swivelling/tilting axis see p. 19

			T1-913520 TAP5	T1-915520 TAP5	T1-913520 TAP5v	T1-915520 TAP5v
Weight (aluminum base plate)	Weight (aluminum base plate)		181/18	181/184 (155) 206/209		
Spindle through-bore		mm	64			
Clamping torque	4th axis	Nm		max.	. 800	
at max. 5 bar air pressure	5th axis	Nm		2,0	000	
Spindle load (max. permissible)	-)	kg	4	0	9	00
Axial force (max. permissible)	<b>※</b>	kN		2	0	
Dull authorize	clamped	Nm		1,0	000	
Pull-out torque	unclamped	INIII		40	00	
Moment of inertia	Standard load	kgm²	0.07	0.2	0.07	0.2
Moment of Inertia	J max		0.7	2	0.7	2
	4th axis Fanuc		4			
	5th axis Fanuc		28 / 10**	28 / 31**	63 / 53**	63 / 40**
Positioning accuracy +/-	4th axis Siemens 1-head		11 (6*)			
(unloaded, -90 to +90°)	5th axis Siemens/Mavilor		28 / 10**	28 / 31**	63 / 53**	63 / 40**
	4th axis Siemens 2-head	± arc sec	3 (2*)			
	5th axis Siemens/Mavilor		28 / 10**	28 / 31**	63 / 53**	63 / 40**
	4th axis Mitsubishi		11 (6*)			
	5th axis Mitsubishi		28 / 10**	28 / 31**	63 / 53**	63 / 40**
repeat acouracy .,	4th axis	arc sec	±1			
(unloaded)	5th axis	aic sec	±2			
	4th axis 90°		0.19	0.24	0.19	0.24
Cycle time with standard load	5th axis	sec	0.48	0.48	0.46	0.46
(without clamping)	4th axis 180°	360	0.24	0.3	0.24	0.3
	5th axis		0.6	35	0.	61

5th axis optional with WMS: see  ${\bf p.~22}$ 

\* Option: WMS.91x-GEN

\*\* with standard load



#### T1-913520 TAP5v / T1-915520 TAP5v



Note: Simultaneous machining with the swiveling/tilting axis must be avoided because of eccentricity.

#### **Available combinations**

	Dividing lindaying avia makes*	Controlling/tilting and proster
	Dividing/indexing axis motor*	Swivelling/tilting axis motor
T1-913520 TAP5	MOT.ET-A	
T1-915520 TAP5	MOT.ET-B	See table below
T1-913520 TAP5v	MOT.ET-A	See table below
T1-915520 TAP5v	MOTET-B	

<sup>\*</sup> Motor data: see p. 15

Drive data Tilting/swivelling axis 520 (based on standard load cube)			<b>∑</b> ) +⊪	7	90°	180°
		Motors	Feed* [Nm]	Speed [rpm]		time*** ec]
MAVILOR / MOVINOR **	TAP5	LN-098	440	30	0.61	1.11
WAVILOR / WOVINGR	TAP5v	LIN-090	440	25	0.73	1.33
FANUC	TAP5	α4 (HV)is	355	28	0.68	1.22
FAINUC	TAP5v		355	25	0.76	1.36
MITSUBISHI 200V	TAP5	HG105	440	28	0.65	1.19
WII I SUDISHI 200V	TAP5v		440	25	0.73	1.33
MITSUBISHI 400V	TAP5	HG-H105	440	28	0.65	1.19
WII I 30013F11 400V	TAP5v		440	25	0.73	1.33
SIEMENS	TAP5	1FK7042	435	30	0.62	1.12
SIEWENS	TAP5v	1FK/042	435	25	0.73	1.33

<sup>\*</sup> at 1 rpm

## **Eccentric version for shorter travel**

#### For swivelling/tilting axis



Labyrinth seal (cutaway view)

Recommended for:

- Grinding operations
- High coolant pressures
- Extremely fine abrasive particles

#### Important information

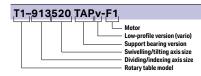
- The limit values as set out in the corresponding parameter list take precedence over the data and information provided in the main catalog (due to motor, drive enhancement and the respective machine CNC)
- Motor-independent data are optimum values at operating temperature
   Further details are available at
- Further details are available at www.lehmann-rotary-tables.com, under Download / Commissioning

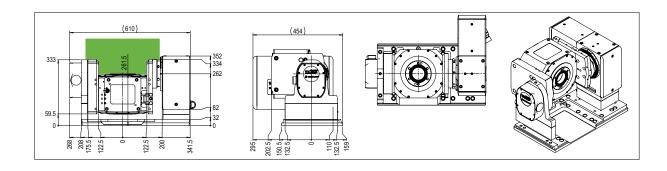
#### Options

Item no.	Description
GET.5xx-GEN	Increased gear precision*
SPI.5xx-Lab	Spindle seal with labyrinth, integrated sealing air pressure control

<sup>\*</sup> incl. increased radial and axial run-out 0.003 mm

#### Item no.





<sup>\*\*</sup> for Siemens / Heidenhain

<sup>\*\*\*</sup> without clamping

## Maximum possible standardization simplifies startup and service

#### Cabling

Cable set, complete, as follows:

- incl. HARTING connector, incl. wall bushing
- only 1 connector per axis
- bifunctional wall bushings for cab wall as well as for cabinet
- mounted and tested at factory, plug&play

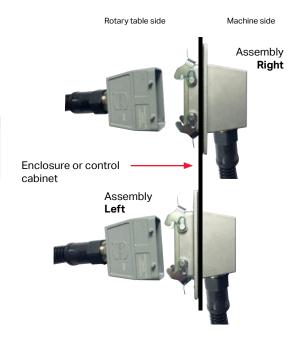
Designation

#### **Order items**

KAB.F9-4.0-FNC	Fanuc DD, fully cabled	4 m, to FANUC CNC
KAB.F9-4.0-M4g	Fanuc DD, fully cabled	4 m, straight HARTING connector
KAB.S9-4.0-M4g	Siemens DD, fully cabled	4 m, straight HARTING connector
KAB.MI9-4.0-M4g	Mitsubishi DD, fully cabled	4 m, straight HARTING connector
Item no.	Designation	Dimensions
WDF.F9-M4	Wall bushing	per axis for Fanuc
WDF.S9-M4	Wall bushing	per axis for Siemens
WDF.MI9-M4	Wall bushing	per axis for Mitsubishi

#### Standard items included in delivery

Always supplied as standard (except Fanuc Robodrill)



#### **FANUC Robodrill**

Automatic parameter setting by program (included in delivery)

Item no.	Designation	Dimensions
KAR EQ-E O-EAG	Fanue DD fully cabled	Pohodrill



Supplied with FANUC interface, compatible with FANUC DDR



#### Machine preparation

- 80A servo required
- Additional CNC options may be needed, for instance, for rotating function, radius compensation, constant cutting speed, pole detection, 5-axis function for simultaneous operation
- PLC must be prepared and adapted accordingly





Separate cabinet with mobile multi-functional manual operating device which can be used for both this CNC system as well as for machines equipped with FANUC CNC.



#### **Order items**

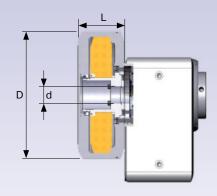
Item no.	Designation	Dimensions / remarks
CNC.1AX-FA-DD	CNC Fanuc 35iB DD, 1-axis (200V)	
CNC.2AX-FA-DD	CNC Fanuc 35iB DD, 2-axis (200V)	
CNC.MFK	M-function cable	Only in conjunction with CNC.1AX-FA-DD or CNC.2AX-FA-DD
CNC.HaKab-10m	Mobile-phone cable	10 m
CNC.BAT	Backup battery option	Only in conjunction with CNC.1AX-FA-DD or CNC.2AX-FA-DD
CNC.Trafo	Transformer	for Fanuc-CNC (400 V to 200 V)
CNC.TRE	Option: Indexing calculator	

#### **Technical data**

Features	Specifications	Remarks
1. Programmable angle	0.001 9999.999°	freely programmable
2. Sub-programs	Yes	can be nested in 4 ways
3/ Total storage capacity	4000 characters (bytes)	Optional 128 kBytes
4. Number of programs, incl. macros	63	Optional 400
5. Program storage buffering	via battery	
6. Programming options	Absolute, incremental	can be combined in any way you wish
7. Reference point approach	Yes	optional absolute
8. Reference point shift	Yes	via parameters
9. Manual feed	creep, rapid traverse, gradual	
10. Feed programming	Yes	
11. Repeat function	programmable loop	
12. Software range limit switch	Yes	adjustable via parameters
13. Hardware range limit switch	Yes	
14. Spindle clamping	automatic	can be switched on / off
15. Monitoring of spindle clamping	Yes	
16. «Rotary table in position» output	Yes	
17. External «Manual/Automatic» input	Yes	
18. «Ready for operation / fault detection» output	Yes	
19. External «Enable turning» input	Yes	
20. Free M-function outputs	5x	e.g. to activate an automatic tailstock
21. «External cycle start» input	Yes	
22. «External cycle stop» input	Yes	
23. «External EMERGENCY STOP» input	Yes	1-channel
24. OK button	single stage	
25. Fault message system on manual control pendant	Clear text	
26. Motor output	AC servomotor	1 or 2 axes
27. Motor measuring system input	FANUC serial	
28. Power supply	200240 VAC 50/60 Hz	3-phase
29. Interface	USB slot, PC card	Ethernet (option)
30. Minimum required signals from the machine	acknowledgeable M-function EMERGENCY STOP connection	if connection to machine CNC required
31. External single block position specification	via RS232 option	not provided
32. Program skips	by using GoTo command	must be done with block numbers (Nxxxx)
33. Continuous turning	Yes	e.g. for grinding work
34. Sub-programs	Yes	can be nested in 4 ways
35. External «EMERGENCY STOP» output	Yes, from manual operating device	1-channel



For the highest indexing accuracy Fully encapsulated, leak-proof, protected against impact, adjusted in a highly precise manner



#### Angular position measuring system required for series 900

	Preparation	Measuring system
Fanuc	WMS.91x-VorFA	WMS.91x-FA
Siemens	WMS.91x-VorSI.1	WMS.91x-Sl.1, 1 x reading head
Siemens	WMS.91x-VorSI.2	WMS.91x-SI.2, 2 x reading head
Mitsubishi	WMS.91x-VorMI	WMS.91x-MI

#### Optional angular position measuring system for series 500 (TAP5 and TAP5v)

#### Add-on parts, assembly and measurement

	Item no.	d	D	L	Weight [kg]	520
Dunnaustian	WMS.520-Vor2	15	130	92	2.82	034
Preparation	WMS.520-Vor7	46	220	87	6.41	2

#### Angular position measuring system (encoders)

 $The angular position \ measuring \ system \ option \ always \ includes \ radial \ and \ axial \ run-out \ of \ the \ spindle \ of \ 0.003 \ mm$ 

	Item no.	Designation	System accuracy [arc sec]	Weight [kg]	Remarks	
	WMS.2580	RCN 2580, Endat/1Vss (replaces RCN 228)	± 2.5	1.03		1
	WMS.275	RON 275, 5VTTL	± 5	0.88	Haas/Hurco	1
<u>.</u>	WMS.8390F	RCN 8390F, Fanuc	± 2	2.73	ø 60 mm	2
nhai	WMS.8390M	RCN 8390M, Mitsubishi	± 2		ø 60 mm	2
Heide	WMS.8380	RCN 8380, Endat/1Vss	± 2	2.73	ø 60 mm	2
풀	WMS.8590F	RCN 8590F, Fanuc	± 1	2.73	ø 60 mm	2
	WMS.8590M	RCN 8590M, Mitsubishi	± 1		ø 60 mm	2
	WMS.8580	RCN 8580, Endat/1Vss	± 1	2.73	ø 60 mm	2
gale	WMS.RU97A	RU97A, Siemens driveCliq (only for Solution Line)	± 2.5			3
gnes	WMS.RU77F	RU77, Fanuc	± 2.5			4
Mag	WMS.RU77M	RU77, Mitsubishi	± 2.5			4



Heidenhain RxN 2xxx Passage: ø 20



Heidenhain RxN 8xxx Passage: ø 60



Magnescale RU 97



Magnescale RU 77

#### Alternative to angular position measuring system

Item no.	Designation
GET.520-GEN	Optional increased mechanical gear accuracy

#### Measuring method used to determine the gear unit's accuracy to VDI/DGQ 3441 or ISO 230-2

Measuring and recording the

angular accuracy, important application

- Measured at operating temperature of the unit after 5 warm-up cycles
- 5 Measuring cycles

information

- 24 measuring points (15°-steps)
- Acceleration 500°/s²
- All measured values apply in the unloaded condition at an ambient temperature of approx. 22°C
- The values WITHOUT load apply

Please note: Due to the influence of environmental factors during the measurement (temperature, vibration...), the recorded measurement error may exceed the catalog limit value by up to 10%.

#### Elasticity of swivelling/tilting axes TAP5\*\*

(reference values for pitch error)

	Unloaded	Standard load sls <sub>cube</sub> *
0°90° [arc sec]		
T1-913520 TAP5	-19	+1
T1-915520 TAP5	-19	+22
T1-913520 TAP5v	-55	-45
T1-915520 TAP5v	-55	-32

<sup>\*</sup> see p. 34

**Explanation:** The pitch error corrects the positioning error resulting from elasticity and caused by the eccentric load of the dividing/indexing axis on the swivelling/tilting axis.

**Recommendation:** In order to achieve the best possible accuracies, we always recommend compensating for the gear backlash and the pitch error (5th axis) with the CNC control unit and/or by using a direct angular position measuring system (option, **p. 22**). A tilting range of 180° results in other compensation values; please contact the factory if necessary.

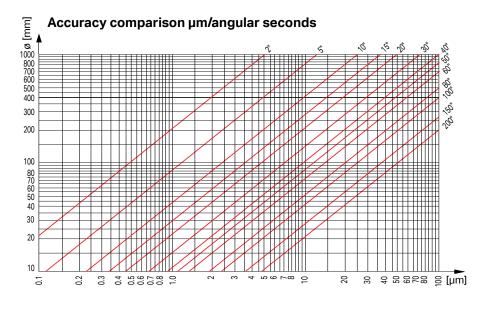


Diagram for determining the relationship between angular seconds and µm on the basis of diameter

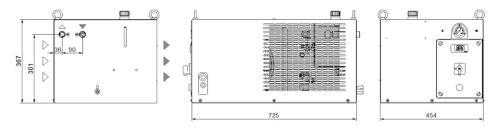


<sup>\*\*</sup> Swivelling/tilting axes with direct drive do not have a pitch error

Recommended cooling units (e.g. for dry-machining at high speeds) and temperature module for machines with SIEMENS and Mitsubishi-CNC

#### **OLAER** cooling unit





#### Order items

Item no.	Designation
AGG.OL-CW12*	OLAER Minichiller CW12, net cooling capacity approx. 1'300 W, incl. cooling lines and connection to rotary table

<sup>\*</sup> Installation by customer or on request by pL LEHMANN (e.g. in the course of commissioning)

#### Temperature protection module (for Siemens and Mitsubishi)

Item no.	Designation
MOTTemn	IMTHP module incl. connecting stranded wire 24V





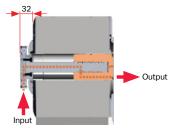
### **Rotary union**

- Up to 250 bar or 500 rpm
- Low maintenance, compact
- Simple, suitable for retrofitting



#### Rotary union for EA rotary tables

Up to 250 bar or 500 rpm

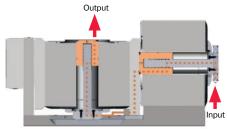


Rotary union, 4- or 6-passage

#### DDF 4-passage (WITHOUT motor cooling)



#### Rotary union for T-type rotary tables



TAP9: with rotary union, 4-passage (partial axis or 6-passage swivelling/tilting axis; 2 passages reserved dividing-axis motor cooling).

#### DDF 4-passage (WITH motor cooling)





DDF.91x-04-d80



DDF.91x-0x





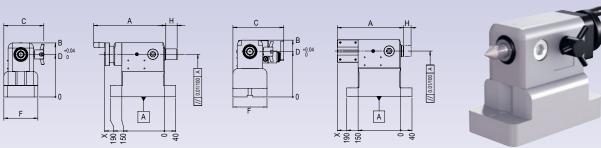
#### Pressure-speed data for rotary union

Avoid high and longer lasting speeds under pressure if possible

(greatly reduces seal life).
For safety reasons, we also recommend «pressureless clamping»

#### **Order items**

Item no.	Designation
DDF.91x-04	Rotary union, 4-passage, oil/air, for dividing/indexing axis
DDF.91x-04-hs	Rotary union, 4-passage, oil/air, for dividing/indexing axis, Highspeed
DDF.91x-04-d80	Rotary union, 4-passage, incl. spindle adapter Ø80
DDF.91x-04-KK5	Rotary union, 4-passage incl. spindle adapter KK5
DDF.91x-06	Rotary union, 6-passage, oil/air, for dividing/indexing axis
DDF.91x-06-TAP9	Rotary union, 6-passage, oil/air, for swivelling/tilting axis (2 cooling passages)
DDF.918-06- TAP9v	Rotary union, 6-passage, oil/air, for swivelling/tilting axis (2 cooling passages)
DDF.520-06-TAP5	Rotary union, 6-passage, oil/air, for swivelling/tilting axis (2 cooling passages)
DDF.TxP9-AGG	Piping (handshake), 2-passage, for cooling unit
DDF.TxP9-DDF	Piping (handshake), max. 4-passage, for rotary union
DDF.TxP9-SPZ	Piping (handshake), max. 4-passage, for release cylinder



measured without load, quill extended halfway

#### Pressure-force diagram

#### Suitable alignment elements

Item no.	Designation	Slot width
AUR.zX-12	zentriX alignment pin, 1 pair	12g6
AUR.zX-14		14g6
AUR.zX-16		16g6
AUR.zX-18	i paii	18g6





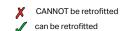


Manual version (right-hand)

Pneumatic version (right-hand)

Hydraulic version (right-hand)

Standard design for all types = (as shown at very top)



				Α	В	С	F	Н		Pneuma-			×	
_		Item no.	Designation	[mm]	[mm]	[mm]	[mm]	[mm]	Manual	tic 2)	Hydraulic 3)	0 - 0-	^	<b>√</b>
		RST.COM-110m 4)	COMPACT tailstock	222	128	130	100	30	•			11		•
	110	RST.LIG-110m	LIGHT tailstock	255		142		40	•			20		•
	' ' '	RST.LIG-110p 1)	LIGHT tailstock	225	150	184	120	40		•		20		•
		RST.LIG-110h 1)	LIGHT tailstock	229		168		40			•	24		•
		RST.COM-150m 4)	COMPACT tailstock	222	168	130	100	30	•			16		•
Ē	150	RST.LIG-150m	LIGHT tailstock	255		142		40	•			25		•
투	130	RST.LIG-150p 1)	LIGHT tailstock	238	190	184	120	40		•		25		•
崖		RST.LIG-150h 1)	LIGHT tailstock	230		168		40			•	29		•
eig.		RST.LIG-180m	LIGHT tailstock	255		142		40	•			30		•
Ě	180	RST.LIG-180p 1)	LIGHT tailstock	238	220	184	120	40		•		30		•
Center height D [mm]		RST.LIG-180h 1)	LIGHT tailstock	230		168		40			•	34		•
ق		RST.LIG-220m	LIGHT tailstock	255	260	142		40	•			35		•
		RST.LIG-220p 1)	LIGHT tailstock	238		184	120	40		•		35		•
		RST.LIG-220h 1)	LIGHT tailstock	230		168		40			•	40		•
	280	RST.LIG-280m	LIGHT tailstock	255	310	142		40	•			42		•
		RST.LIG-280p 1)	LIGHT tailstock	238		184	120	40		•		42		•
		RST.LIG-280h 1)	LIGHT tailstock	230		168		40			•	47		•
		RST.L-m	Left-hand version, manual											•
	ω	RSTL-p	Left-hand version, pneumatic									•		
	rie	RST.R-poh	Pneumatic, without manu	ıal lever va	alve								•	
	SS	RST.L-poh	Left-hand version, pneumatic, without manual lever									•		
	8	RST.L-h	Left-hand version, hydrau	ulic									•	
	₹	RST.R-hoh	Hydraulic without manua	l lever val	ve								•	
	6	RST.L-hoh	Left-hand version, hydrau	ulic, witho	ut manua	l lever va	lve						•	
	pti	RST.Hub-p	Stroke monitoring for tail	stock (pn	eumatic),	free cabl	le ends 5	m of whic	h 4.5 m in fle	xible tubing; s	troke 5 mm sl	horter	•	
	Š O	RST.Hub-h	Stroke monitoring for tail	stock (hy	draulic), fr	ee cable	ends 5 m	of which	4.5 m in flexi	ble tubing; str	oke 5 mm sho	orter	•	
	ţ	RST.SPI-MK2s	Fixed center, hardened st	teel				MK2						•
Γ	Tailstock Option / Accessories	RST.SPI-MK3s	Fixed center, hardened st	teel				MK3						•
	F	RST.SPI-MK2hm	Fixed center, HM use					MK2						•
		RST.SPI-MK3hm	Fixed center, HM use					MK3						•

All LIGHT tailstocks: Parallelism of quill axis to alignment groove adjustable thanks to zentriX system (see operating manual)

Morse taper size (DIN 228): COMPACT = MK 2, LIGHT = MK 3

Delivered as standard with manual lever valve. Connection plate for external hydraulic supply is a special model, please contact factory.

<sup>&</sup>lt;sup>2</sup> Impact force approx. 660...2'000 N at 2...6 bar air pressure
<sup>3</sup> Impact force approx. 3'800 N at max. 24 bar oil pressure
<sup>4</sup> Delivered with center height +/-0.01 mm

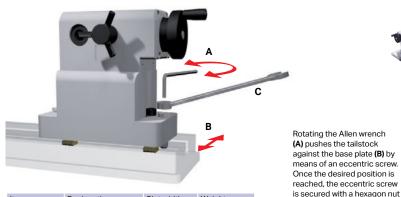
### Align and secure correctly on the machine table:

#### lineFIX and zentriX



Nut

#### zentriX alignment system (example: tailstock on longFLEX)



Item no.	Designation	Slot width	Weight [kg]
AUR.zX-12		12g6	0.10
AUR.zX-14	zentriX alignment	14g6	0.10
AUR.zX-16	pin, 1 pair	16g6	0.11
ALID 7Y-18		1806	0.12

#### available for ...







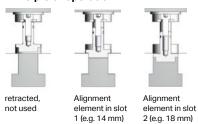
information, please refer to the	
installation and commissi-	
oning instructions at: www.	
lehmann-rotary-tables.com	

#### lineFIX alignment system for T-type rotary tables (not for TIP)



As a standard feature, every T-type rotary table has one lineFIX pin (for a slot width of 14 or 18 mm). Every base plate has a hole pattern that matches a T-slot spacing of 100  $\,$  mm and 125  $\,$  mm. After being set up initially with the **lineFIX** pin, the rotary table undergoes final adjustment and is then secured in position using these holes.

#### Principle of operation



(C). Finished. For additional

lehmann-rotary-tables.com

Item no.	Designation	Slot width	Weight [kg]
AUR.iX-12-16	Option (2 pieces)	12/16	
AUR.iX-14-18	Standard (2 pieces)	14/18	0.03
LOZ.Bride-L	Long clamps, for 63/ pattern*	125 grid	0.93

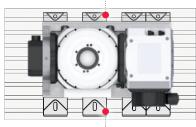
<sup>\*</sup> When installed properly as described in the operating manual, the hold-down force per clamping claw (short or long) is 20 kN.

#### Version with clamping claws

If no hole pattern matches the slots, the rotary table can be secured by means of clamping claws.

Screw

Short clamping claws (standard scope of delivery)

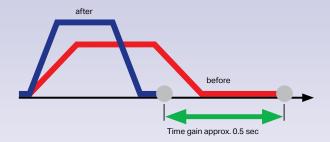


Long clamping jaws (item no.: LOZ.Bride-L): for making adjustments when mounting in intermediate positions

#### **Small parts**

			Mainte- nance unit	Clamps, steel plugs	Gear oil, clamps, steel plugs	Fastening material on machine table (screws,
LOZ.91x-EA		EA-91x	х	x		
LOZ.91x-TAP9		T1-91x91x TAP9(v)	x	x		
LOZ.91x-TAP5		T1-91x520 TAP5(v)	x		x	
LOZ.FAN-TAP9	Fanuc Robodrill	T1-91x91x TAP9(v)				x

We support you from A to Z, whether you have problems or when it's a matter of optimization



Optimization of the cycle time (CMS position)

#### **Commissioning Service**

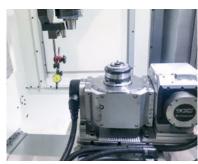
Commissioning of new machines with controls from Siemens, Fanuc, Mitsubishi, Mazak. In addition to basic commissioning (see p. 31), we optimize for positioning and simultaneous operation through our application support on request.

Improved application, optimal adjustment of rotary table and machine, higher productivity

For item no., see p. 32















Maximum productivity requires that your application be taken in account we can help you

Optimally clamped? We can also provide on-site assistance in this regard.

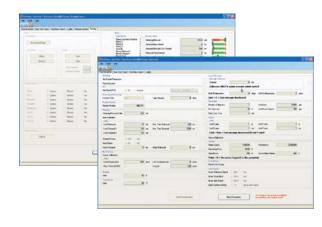
#### **Helpline Service**

Telephone service from 7:30 a.m. – 12:00 noon and 2:00 p.m. - 5:00 p.m. as well as 24-h/5 telephone emergency service for all pL service centers

- Technical assistance
- Diagnostic support
- Organizing factory and field service
- Taking spare part orders

#### Goal

To help quickly, competently and unbureaucratically





#### **Application Support**

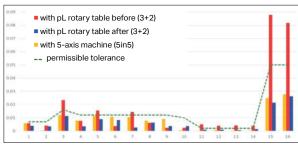
Experience has shown: A considerable improvement in time needed per piece and workpiece accuracy are almost always possible.

- Adjustments for spindle operation
- Reliable clamping control.
- General support for lathing/milling operation with BR900
- Safeguarding the equipment against overheating
- Support with PLC adjustments
- Clamping the workpiece correctly, optimizing machining
- Improving workpiece accuracy (alignment, 0-point...)
- Fine-tuning of drives and CNC parameterization

#### Goal

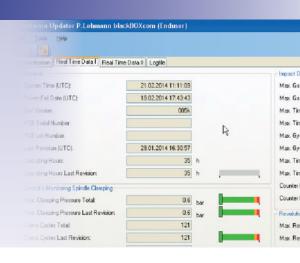
To extract the maximum, improve efficiency, lower workpiece costs, increase workpiece accuracy

For item no., see p. 32



Errors at the measuring points before and after APS precision for 3-D machining.

We also support you after the purchase to ensure high availability of your equipment



#### Active Service1)

#### 101.70 00.7100

- Visual inspection
- Hose check

**Easy Check** 

- Read and evaluate blackBOX data
- Status report with recommendation

#### Facts

- Without maintenance contract
- We schedule the region on our own
- Then notify the intended customers of the pending visit
- Customers can decide yes or no

1) an excerpt from our Active Services; please contact us for additional options

#### **Benefits**

- Prevention helps to minimize expensive downtime
- Travel costs are prorated
- The customer does not need to think about it
- No contract, you are free to decide annually
- Based on the worldwide practical experience of pL

#### Goal

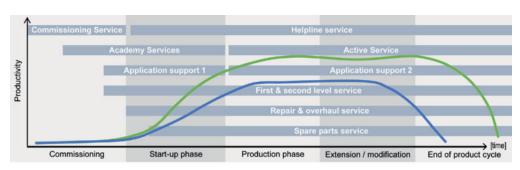
Prevent downtime, eliminate stress and costs, extend the service life → Prevention instead of reaction





Status report with recommendation

#### LifeCycle Services: Increased productivity over the life of your machine ...



Productivity with LifeCycle service products from pL LEHMANN
Productivity without service support

Investigations have shown that 70% of problem situations during the warranty period can be prevented through careful and professional commissioning. At the same time, it was

obvious that productivity could be increased significantly through use of application service. Make use of our services!

#### **Basic commissioning**

#### Goal

Rotary cable connected and parameterized, ready for production

#### **Activities**

- Mechanical assembly of the rotary table on the machine table
- Alignment of the rotary axes with respect to the main axes of the machine
- Kinematics setting/check
- Electrical connection of the rotary table on the machine
- Basic parameterization using pL parameter lists, at least with usual values, but possibly to customer requirements
- Brief customer training

#### Prerequisite

- Machine must be prepared appropriately (servo, control cabinet cabling, connectors, PLC, CNC with readily available 4th and/or 5th axis/axes; or can be ordered from pL LEHMANN (depending on machine; PLC not possible)
- During commissioning, a qualified technician from the machine supplier may be need to be present (parameter adjustments, possibly adjustment of the PLC etc.); organized and paid by customer, contact us with the request.

#### Commissioning of servopack

#### Goal

Connection of the rotary table and adjustment to customer requirements if possible, incl. integration of the Servopack retrofit kit

#### Activities

- ServoPack installation with cabling in control cabinet up to enclosure wall
- Mechanical assembly of the rotary table on the machine table
- Alignment of the rotary axes with respect to the main axes of the machine
- Kinematics setting/check
- Electrical connection of the rotary table on the machine
- Basic parameterization using pL parameter lists, at least with usual values, but possibly to customer requirements
- Brief customer training

#### Prerequisite

- Machine must be prepared appropriately (CNC has readily available 4th and/or 5th axis, PLC is prepared)
- During commissioning, a qualified technician from the machine supplier may be need to be present (parameter adjustments, possibly adjustment of the PLC etc.); organized and paid by customer, contact us with the request.





#### **Commissioning of M-function**

#### Goal

FANUC 35i linked to machine's CNC via M-function

#### Activities

- Cabling from the FANUC 35i to the interface on the machine's CNC
- Function test and brief training of the operator
- Linking of EMERGENCY STOP, if possible

#### Prerequisite

 Machine and CNC must be prepared appropriately (readily available M-function)

#### Note

Please note that we offer training for the operation of the Fanuc 35iB controller in our Academy.

#### **Application support**

#### Goal

Rotary table settings optimized for customer application (time optimization and/or accuracy improvement)

#### Activities

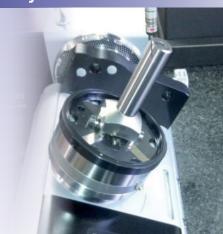
- Calculation based on rotary table and workpiece (what is possible)
- Check of the geometry, and correct as much as possible
- Check whether the clamping control functions correctly and is not active before the intended position is actually reached
- Check of dividing/indexing errors (0–90° relatively simple; possibly with portable measuring instrument)
- Check of clamping/load placement (no overly eccentric loads, improper clamping), and of the machining sequence and the control response (smooth control)
- Adjustment of gear backlash and pitch error
- Optimization for specific workpiece, incl. clamping device and machining strategy (may require considerably more effort for simultaneous machining; invoiced separately)
- Kinematics setting/check
- Expenses such as travel time, travel costs, hotel and meals are calculated on the basis of actual cost

#### Prerequisite

 Programming system must be prepared appropriately (e.g. for simultaneous operation)

	Item no.	Data	Description		
e s	INB.1AX-APS	max. 15 h, 1-axes	Application support		
-type ro- ry tables	INB.1AX-CMS	basic, max. 10 h, 1-axes	Commissioning of integrated axes		
ta E	INB.1AX-SP	max. 15 h, 1 axes	Commissioning of servopack		
-o s	INB.2AX-APS	max. 20 h, 2-axes	Application support		
type ro-	INB.2AX-CMS	basic, max. 15 h, 2-axes	Commissioning of integrated axes		
草크	INB.2AX-SP	max. 20 h, 2 axes	Commissioning of servopack		
with pL CNC	INB.MF	max. 15 h on-site	Commissioning of M-function		

High geometric accuracies as standard, combined with a high level of rigidity and stability
And for the most demanding requirements:
1/2 tolerance as an option



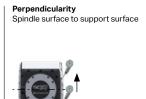
() values = increased accuracy. Item no.. GEO.5xx-GEN

#### The tolerances given below apply under the following conditions:

- 1. The rotary table is mounted as specified in the commissioning instructions
- 2. The measurement is carried out on a calibrated granite plate (all machine errors are excluded)
- 3. The rotary table is not subjected to any outside thermal influences (sun, fans, heaters...)
- 4. Prior to the measurement, the rotary table and the measuring and test equipment have been in the same environment for at least 24 h
- 5. All measured values are determined for an unloaded rotary table

#### Geometry of EA rotary tables



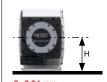


0.01/100 mm (0.005/100 mm)



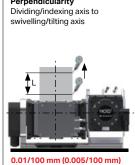
0.01/100 mm (0.005/100 mm)

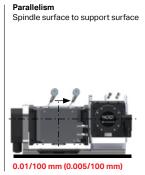
## Center height

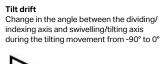


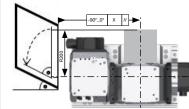
#### Geometry of T1 rotary tables











0.01/R150 mm (0.005/R150 mm; applies

#### For all rotary tables

#### Radial and axial run--out for all rotary table versions

- measured at spindle nose
- Axial concentricity on largest diameter
- Radial concentricity of inner bore as well as centering ø



0.006 mm (0.003 mm)

Basics of the drive data

All drive data of pL-LEHMANN rotary tables have been designed for the following standard spindle loads in accordance with DIN/VDE 0530 as follows:

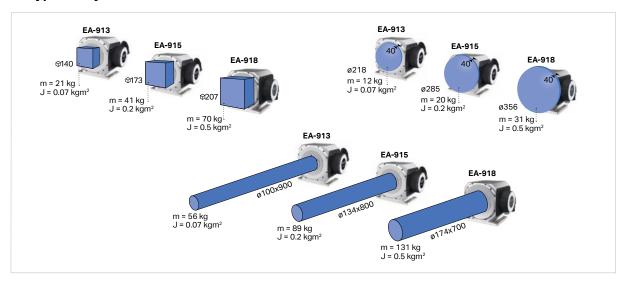
- For intermittent service S3 ED 40%
- Cycle duration 10 minutes

Different conditions require the drive data to be adjusted (acceleration, jerk limitation, speed).

#### Reference values for duty cycle (ED)

- For normal rotary table work such as milling / boring (mainly positioning) approx. 20%.
- For milling / boring in intensive mixed operation (positioning / feed machining): approx. ED 40%
- For profile and depth grinding approx. ED 60% / simultaneous machining, 5-axis
- For engraving and operations in spindle mode approx. ED 80–100%.

#### **EA-type rotary table**



#### T1-type rotary tables (TAP)



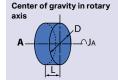


#### We are here to help

Request a proposal and we will gladly prepare you an offer for your individual calculation up to and with a specific list of parameters. Contact your closest pL LEHMANN representative. We are here to help.

#### Calculation of the load on the dividing/indexing axis

(using Steiner's theorem)



- D: Outside diameter of the round bar [m]
- L: Length of the round bar [m] p: Density [kg/m³]
- m: Mass of the round bar [kg]
- J.: Moment of inertia [kgm²]

 $J_{\Delta} = J + m \cdot r^2$ 

Center of gravity outside



- D: Outside diameter of the round bar [m]
- Length of the round bar [m]
- Turning radius [m]
- Density [ka/m3]
- m: Mass of the round bar [kg]
- J<sub>a</sub>: Moment of inertia of the round bar at center A [kgm²]
- J: Moment of inertia [kgm²]

Center of gravity in rotary



Center of gravity in rotary

- Outside diameter of the cylinder [m]
- Bore diameter of the cylinder [m]
- L: Length of the round bar [m]
- Density [kg/m³]
- m: Mass of the cylinder [kq]
- J<sub>a</sub>: Moment of inertia [kgm²]
- a: Side length [m]
- Side length [m]
- Side length [m]
- Density [kg/m³]
- J<sub>A</sub>: Moment of inertia [kgm<sup>2</sup>]
- m=a·b·L·p

 $J_A = \frac{1}{9} m (D^2 + d^2)$ 

 $J_A = \frac{1}{12} m (a^2 + b^2)$ 

 $m = \left(\frac{D^2 \cdot \pi}{4} \cdot L \cdot p\right) \cdot \left(\frac{d^2 \cdot \pi}{4} \cdot L \cdot p\right)$ 



- Side length [m]
- Side length [m] Side length [m]
- Density [kg/m³]
- r: Turning radius [m] J<sub>a</sub>: Moment of inertia [kgm²]
- $m = a \cdot b \cdot L \cdot p$
- $J_A = \frac{1}{12} m (a^2 + b^2 + 12r^2)$

Dividing/indexing axis

Swivelling/tilting axis

Radius between swivelling/tilting axis and spindle nose of dividing/indexing axis [m]

Center distance [m]

= Mass [kg]

Torque calculated from  $m \times g \times Rs$  [Nm]

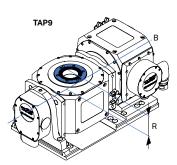
Torque acting on the swivelling/tilting axis caused by the dead weight of the dividing/indexing axis [Nm]

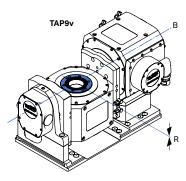
Acceleration due to gravity 9.81 [m/s<sup>2</sup>]

#### Densities of different materials x dynamic speed (p)

Steel 7.85 x 103 kg/m3 Cast iron 7.85 x 103 kg/m3 Aluminum  $2.7 \times 10^3 \, kg/m^3$ Copper  $8.94 \times 10^3 \, kg/m^3$ 8.5 x 10<sup>3</sup> kg/m<sup>3</sup>

#### Calculation of the load on the swivelling/tilting axis





#### Distance R

Rotary table	R [mm]	Limited torques [Nm]
T1-91x915 TAP9	69.5	36
T1-91x918 TAP9v	0	77
T1-91x520 TAP5	69.5	100
T1-91x520 TAP5v	0	100

Calculation of the torque in the tilting direction (without intrinsic torque of the dividing/indexing axis):

Rs = R + L/2 $M = m \times Rs \times g$ 

Calculation of the total torque in the tilting direction (with intrinsic torque of the dividing/ indexing axis):

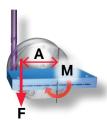
M tot = M + Me (Me represents the gear unit loading without load)

## Reference values for configuring and selecting the correct rotary table

F = Feed force, A = Distance [m] from rotary table axis to feed force (F) during machining, M = Resulting torque (FxA) Resulting torque M = F x A  $\rightarrow$  must not exceed the max. clamping torque [Nm] or max. feed torque [Nm] of the rotary table!

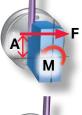
V = Rough machining, WP = indexable inserts, VHM = Solid hard metal

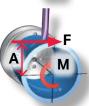
#### **Drilling**



	Wz ø	Cutting speed	Feed F		Feed force F [N]	
Tool type	[mm]	[m/min]	[mm]	CK45	X5CrNi18-10	AIMg4.5Mn0.7
		220	0.12	920		
Twist drill VHM	5	120	0.10		1120	
		350	0.15			315
	10	220	0.27	1'450		
Twist drill VHM		120	0.18		1'900	
		350	0.2			650
	17	220	0.35	2'850		
Twist drill VHM		120	0.25		3'980	
		350	0.3			1'250
WP drill		140	0.09	4'350		
	38	100	0.08		6'550	
		180	0.16			2'800

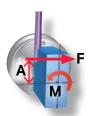
#### End milling and slot milling





	Wzø	Cutting speed	Feed F	Depth of cut	Cutting width		Feed force <b>F</b> [N]		
Tool type	[mm]	[m/min]	[mm]	[mm]	[mm]	CK45	X5CrNi18-10	AlMg4.5Mn0.7	
	_	180	0.09 x 4	4	8	840			
End milling cutter V	8	70	0.06 x 4	4	8		410		
outtor v		570	0.15 x 4	4	8			360	
	12	180	0.11 x 4	6	12	1'100			
End milling cutter V		70	0.07 x 4	6	12		700		
cutter v		570	0.17 x 4	6	12			550	
	20	180	0.095 x 4	10	20	1'550			
End milling cutter V		70	0.08 x 4	10	20		1'400		
		570	0.17 x 4	10	20			950	

#### Hobbing



	Wz ø	Cutting speed	Feed F	Depth of cut	Cutting width				
Tool type	[mm]	[m/min]	[mm]	[mm]	[mm]	CK45	X5CrNi18-10	AlMg4.5Mn0.7	
	_	200	0.09 x 4	8	4	510			
End milling cutter V	8	77	0.06 x 4	8	4		420		
cutter v		627	0.15 x 4	8	4			360	
		200	0.11 x 4	12	6	1'050			
End milling cutter V		77	0.07 x 4	12	6		700		
Cutter V		627	0.17 x 4	12	6			550	
	20	200	0.15 x 4	20	10	2'700			
End milling cutter V		77	0.08 x 4	20	10		1'350		
		627	0.17 x 4	20	10			950	

#### **Turning**



	Turning ø	Cutting speed	Feed		Feed force <b>F</b> [N]		
Tool type	[mm]	[m/min]	[mm]	Depth of cut [mm]	CK45	X5CrNi18-10	AlMq4.5Mn0.7
loui type	Limin	[III/IIIII]	friming	Limin	UK45	ASCHAITS-10	Alivig4.5ivii10.7
Corner		250	0.3	2	541		
	40	140	0.25	2		286	
		500	0.4	3			65.6



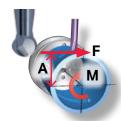
Factory information from well-known tool manufacturers (applies to new tool cutting edges)

### Corner milling (slab milling or plane milling)



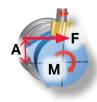
	Wzø	Cutting	Feed	Depth of	Cutting		Feed force <b>F</b> [N]	
Tool type	[mm]	speed [m/min]	F [mm]	cut [mm]	width [mm]	CK45	X5CrNi18-10	AlMg4.5Mn0.7
		160	0.12 x 6	2	40	1'750		
Angular		160	0.12 x 6	2.5	25	1'250		
milling	40	85	0.12 x 6	2	40		1'550	
cutter WP		85	0.12 x 6	2.5	25		1'150	
		500	0.15 x 6	3	40			1'250
		210	0.15 x 10	3.5	80	4'900		
		240	0.15 x 10	7	40	4'900		
Angular milling	80	160	0.08 x 10	3.5	80		3'450	
cutter WP	80	176	0.08 x 10	7	40		3'450	
		450	0.2 x 10	3.5	80			3'100
		495	0.2 x 10	7	40			3'100

### Ball end milling



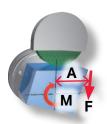
	Wz ø	Cutting speed	Feed F	Depth of cut	Cutting width		Feed force F [N]	
Tool type	[mm]	[m/min]	[mm]	[mm]	[mm]	CK45	X5CrNi18-10	AlMg4.5Mn0.7
Ball end		220	0.1 x 2	1.0	1.0	60		
milling	6	100	0.08 x 2	0.8	0.8		35	
cutter		530	0.15 x 2	2.0	2.0			50
Ball end		220	0.14 x 2	1.3	1.3	100		
milling	12	100	0.11 x 2	1.0	1.0		65	
cutter		530	0.16 x 2	3.0	3.0			85

### Mill turning



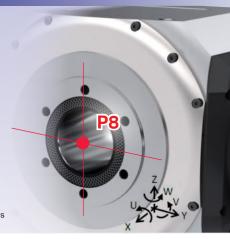
	Wzø	Cutting	Feed	Depth of	Cutting		Feed force F [N]	
Tool type	[mm]	speed [m/min]	F [mm]	cut [mm]	width [mm]	CK45	X5CrNi18-10	AlMg4.5Mn0.7
Angular		130	0.12 x 6	5	1mm / 360°	435		
milling	40	85	0.12 x 6	5	1mm / 360°		390	
cutter		500	0.12 x 6	5	1mm / 360°			193

### Grinding



	Crinding consoits		Feed force F [N]	
Tool type	Grinding capacity [kW]	CK45	X5CrNi18-10	AIMg4.5Mn0.7
Ceramic	40	2200		
grinding	75	4130		
wheel				
CBN grin- ding wheel				
uning writer				

Material elasticities and their effect on workpiece accuracy: Understand them correctly and know how to respond in real-world practice



P8 with EA-type rotary tables

### **Background**

Every material has a certain elasticity. Depending on the orientation and load, these affect the accuracy of machining in different ways. The figures and data shown here provide information on the values to be expected.

### **Optimization options**

If the static stiffness is insufficient, the following may help:

- Error compensation in the axis direction affected
- Use of lighter clamping means
- Changing the machining strategy

### Static mechanical analysis

Using FEM analyses, the compliance in P8 (see figure at right) was calculated in the respective configuration for all T-type rotary tables listed below. The deflections in the X- and Y-directions are usually negligible. The table below shows the deflection in the Z-direction. Depending on the workpiece weight, this information can be used to determine the approximate displacement.

### Compliance of EA-type rotary tables in P8 in Z-direction (approximate values)

μm/kg	Rotary table fastened by means of bolting	Rotary table fastened by means of clamping claws
EA-91x	-0.010	-0.008



### Compliance of T1-type rotary tables in P8 in Z-direction (approximate values)

μm/kg	(	)°	90°								
	TAP9	TAP9v	TAP9	TAP9v							
T1-91x915	-0.017		-0.021								
T1-91x918		-0.018		-0.015							





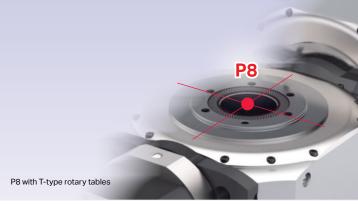
μm/kg	(	)°	9	0°
	TAP5	TAP5v	TAP5	TAP5v
T1-91x520	-0.022	-0.025	-0.035	-0.018



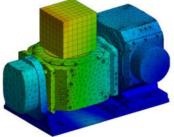


EΑ

## Results of static-mechanical FEM analysis

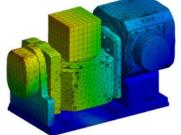




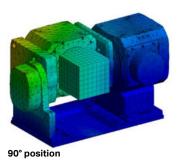


0° position





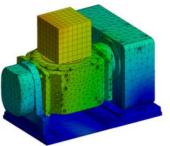
0° position



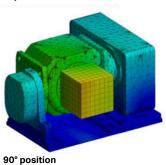
TAP5

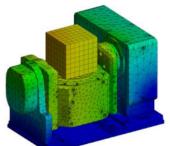
90° position

TAP5v

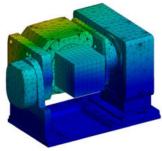


0° position





0° position

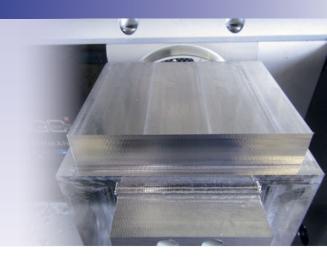


90° position



Condition: Rotary table is mounted in the specified manner and both axes are clamped with 6 bar compressed air.





The illustrations below always show mode 1

### **Dynamic analysis**

The eigenfrequencies were determined using FEM modal analyses. The compliance frequency response curves at the right show the result of the harmonic analysis. The first 9 vibration modes and eigenfrequencies of all rotary tables listed below were determined. Experience has shown the mode 1 and mode 2 are the most important in actual practice. These values can be found in the table below.

### **Optimization options**

If the frequency of the machining process starts to increase, change the following:

- Tool speed
- Number of teeth on tool
- Machining strategy
- Workpiece orientation

Important notice: Shape, weight and the way the workpieces are assembled as well as the clamping devices used can significantly affect eigenfrequency.

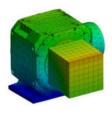
**Condition:** Rotary table is mounted in the specified manner and both axes are clamped with 5 bar compressed air.

### **Example of machining frequency calculation**

Angular milling cutter Ø40 mm, number of teeth 4, speed 1'900 rpm =  $\frac{4 \times 1'900}{60}$  = 127 Hz

### Eigenfrequency of EA-type and M-type rotary tables, mode 1 and 2 (approximate values)

Hz	Rotary table fastene	d by means of bolting	Rotary table fastened by	means of clamping claws				
	without standard load	with standard load	without standard load	with standard load				
Mode 1	443	346	305	263				
Mode 2	727	473	498	379				



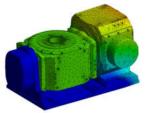
Every object has several natural frequencies (so-called eigenfrequencies) that depend on the object's shape, mass and material. If the machining frequency matches an eigenfrequency, e.g. that of a rotary table, the result is chattering or whistling noises. A vertical machining center has its first eigenfrequency in the range of about 100 Hz. It is important that the machining frequency does not match the eigenfrequency.

The illustrations below always show mode 1

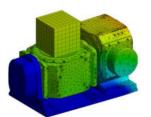
### Eigenfrequency of TAP9-type rotary tables, mode 1 and 2 (approximate values)

Hz		witho	ut load			with	load			
	TA	P9	TA	P9v	TA	P9	TAP9v			
	0°	90°	0°	90°	0°	90°	0°	90°		
Mode 1	231	237	168	172	210	217	159	162		
Mode 2	347	347	196	196	325	340	196	196		

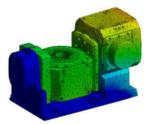




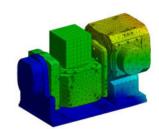
TAP9 without standard load in accordance with **p. 16** 



TAP9 with standard load in accordance with **p. 16** 



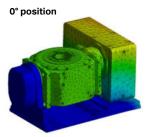
TAP9v without standard load in accordance with **p. 17** 



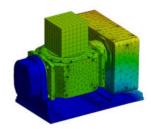
TAP9v with standard load in accordance with **p. 17** 

### Eigenfrequency of TAP5-type rotary tables, mode 1 and 2 (approximate values)

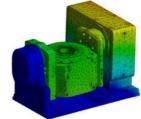
Hz		witho	ut load			with	load		
	T.	AP5	TA	P5v	TA	P5	TAP5v		
	0°	90°	0°	0° 90°		0° 90°		90°	
Mode 1	172	179	136	146	156	164	127	135	
Mode 2	239	239	189	189	220	224	189	189	



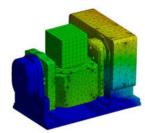
TAP5 without standard load in accordance with **p. 18** 



TAP5 with standard load in accordance with **p. 18** 



TAP5v without standard load in accordance with **p. 19** 



TAP5v with standard load in accordance with **p. 19** 

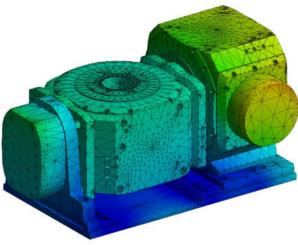
# Thermal deformation from the process and operation

### **Basics**

Heat is generated by friction and electrical losses. The more intense and the longer a motion lasts, the more the temperature rises. Depending on the particular heat sources (motor, gear unit, seals, etc.,) the effects on dimensions differ greatly. At point P8 (see figure to the right), the relevant differences for the workpiece have been determined and are presented in the adjacent tables. The determination was made experimentally and with the aid of simulations.

## Approximate values for estimating the deformations

Approximate values for estimating the thermally induced deformations are listed in the tables on the following pages. All values apply to L-versions; on the R-version, it must be kept in mind that the signs for the directions of rotation are reversed.



Thermally induced deformation in stationary state from the FEM simulation of the T1 91x915 TAP9, positioning application with ED 20%, without cooling lubricant and without cooling unit, deformation shown with 80x increase.

### Influencing factors

The thermally induced deformations occur in response to external (coolant, ambient air, etc.) and internal (gear unit, bearings, motor, etc.) thermal factors. The following factors require particular attention:

- Operating mode of the table (duty cycle, performance, etc.)
- Idle time between the work cycles
- Optional cooling plate (on request) for removing internal heat from the gear unit, bearings, etc.
- Machine table (thickness, size, material) and how the rotary table is mounted on it

### **Example of reading the tables**

For dry simultaneous machining with the T1-913915 TAP9, the table provides a displacement in V-direction at point P8 of 0  $\mu m$  after 60 s after a cold start. This remains for the time being. After approx. 1 hour, a displacement of -1  $\mu m$  occurs, increasing to -5  $\mu m$  after 10 hours. Explanation of behavior: The temperature increases during longer use, causing the displacement.

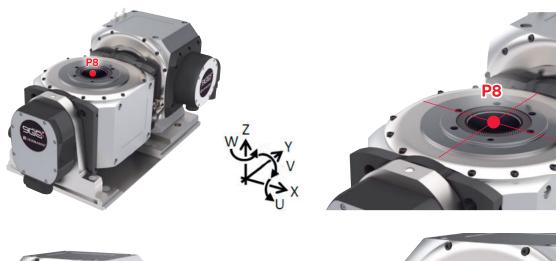


The best cooling is not a substitute for the briefest possible workpiece clamping ...



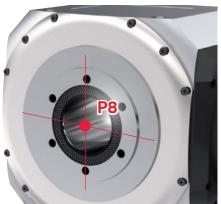
### Measuring point P8

The displacements and rotations are evaluated at point P8, at the center of the spindle surface.



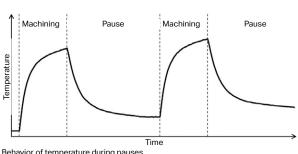






### Important for precision machining

Maximum precision is achieved through use of coolant (KSS). Constant and uniform wetting of the rotary table is recommended. Interruptions in the use of coolant can result in accuracy fluctuations. The most effective heat removal is achieved with water-based coolants that are kept at a constant temperature and distributed uniformly. In addition, pauses and interruptions in machining between individual cycles should be avoided. Relevant cooling and thus deformations can occur even from pauses of one minute.



Behavior of temperature during pauses.

The following values in both tables apply with the rotary table mounted and resting over its entire surface on a solid machine table (steel/cast metal).

W.A.										μm							
× × × × × × × × × × × × × × × × × × ×				X-dis	placer	nent			Y-dis	place	ment			Z-dis	place	ment	
*(>×			1	1.5	3	60	600	1	1.5	3	60	600	1	1.5	3	60	600
<b>P</b> U <sup>©</sup>										[min]							
		EA-91x DD	0	0	0	2	5	0	0	0	0	0	0	0	0	3	9
	Positioning mode	T1-91x915 TAP9	0	0	0	0	0	0	0	0	-1	-5	0	0	0	2	8
- E 3	(spindle clamping	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	-1	-5	0	0	0	2	6
<b>三</b>	active)	T1-91x520 TAP5	16	19	20	6	3	-2	-3	-5	-34	-59	3	4	7	34	65
WELL IN U		T1-91x520 TAP5v	0	0	0	0	0	-2	-3	-5	-34	-59	3	4	7	33	63
Dilloo oo		EA-91x DD	0	0	0	3	9	0	0	0	0	0	0	0	0	4	15
00	Simultaneous	T1-91x915 TAP9	0	0	0	0	0	0	0	0	-2	-8	0	0	0	3	11
Though the state of the state o	machining	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	-2	-8	0	0	0	3	8
A PARTIE A P		T1-91x520 TAP5	16	19	20	6	3	-2	-3	-5	-35	-65	3	4	7	35	69
College Colleg		T1-91x520 TAP5v EA-91x DD	0	0	0	0 41	0	-2	-3	-5	-35	-65 -2	3	4	7	34	65
AND THE PARTY OF T		T1-91x915 TAP9	0	1	3	0	08	0 -1	0 -1	0 -3	-54	-101	2	3	6 5	70 49	155 94
	Turning	T1-91x915 TAP9	0	0	0	0	0	-1 -1	-1 -1	-3	-54	-101	1	2	5	30	56
	rurning	T1-91x515 TAP5	16	19	20	6	3	-4	-6	-11	-101	-205	3	5	10	73	140
1		T1-91x520 TAP5v	0	0	0	0	0	-4	-6	-11	-101	-205	3	5	9	54	103
RESIDENCE OF THE PERSON NAMED IN COLUMN 1		EA-91x DD	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1
	De etti e ete e e e e ete	T1-91x915 TAP9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
NAME OF THE OWNER OWNER OF THE OWNER	Positioning mode (spindle clamping	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	active)	T1-91x520 TAP5	19	21	19	17	17	-3	-5	-6	-9	-10	4	7	9	11	11
Die Control of the Co	•	T1-91x520 TAP5v	0	0	0	0	0	-3	-5	-6	-9	-10	4	7	9	11	11
00		EA-91x DD	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1
D D		T1-91x915 TAP9	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1
ew.	Simultaneous machining	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1
ash	macriming	T1-91x520 TAP5	19	21	19	17	17	-3	-5	-6	-9	-10	4	7	9	11	11
splas		T1-91x520 TAP5v	0	0	0	0	0	-3	-5	-6	-9	-10	4	7	9	11	11
Mit		EA-91x DD	0	0	0	2	2	0	0	0	-2	-2	2	3	5	18	18
The second second		T1-91x915 TAP9	0	0	0	0	0	-1	-1	-2	-8	-8	1	1	3	8	8
WELL THE	Turning	T1-91x915 TAP9v	0	0	0	0	0	-1	-1	-2	-8	-8	1	1	3	6	6
1111		T1-91x520 TAP5	19	21	19	17	17	-5	-8	-11	-26	-27	4	7	9	13	13
Maria Car A Shoot B		T1-91x520 TAP5v	0	0	0	0	0	-5	-8	-11	-26	-27	4	7	9	11	11
		EA-91x DD	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1
	Positioning mode	T1-91x915 TAP9	0	0	0	0	0	0	0	0	0	1	0	0	0	2	2
	(spindle clamping active)	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	0	1	0	0	0	1	2
	, , , , ,	T1-91x520 TAP5 T1-91x520 TAP5v	16 0	18 0	20	7	6	-2 -2	-3 -3	-4 -4	-24 -24	-29 -29	3	4	7	22	27 27
		EA-91x DD	0	0	0	0	1	0	0	0	0	-29	0	0	0	1	1
X Birth Siles		T1-91x915 TAP9	0	0	0	0	0	0	0	0	0	1	0	0	0	2	3
Vate vate	Simultaneous	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	0	1	0	0	0	2	2
With active wat	machining	T1-91x515 TAP5	16	18	20	7	6	-2	-3	-4	-24	-29	3	4	7	22	28
acti acti		T1-91x520 TAP5v	0	0	0	0	0	-2	-3	-4	-24	-29	3	4	7	22	27
E C S S S S S S S S S S S S S S S S S S		EA-91x DD	0	1	3	34	52	0	0	0	1	1	2	3	6	66	124
3		T1-91x915 TAP9	0	0	0	-1	-1	-1	-1	-3	-24	-24	1	2	5	38	44
	Turning	T1-91x915 TAP9v	0	0	0	-1	-1	-1	-1	-3	-24	-24	1	2	5	30	35
		T1-91x520 TAP5	16	18	20	7	6	-4	-6	-10	-89	-152	3	5	10	56	79
		T1-91x520 TAP5v	0	0	0	-1	-1	-4	-6	-10		-152	3	5	9	48	70
	tornoine od svitle the offs						. \A/;+la										

The values for turning have been determined with the flux weakening of the dividing/indexing axis active. Without flux weakening, less thermal load and therefore less displacement and rotation may be expected.

### Duty cycle

Positioning mode: 20% Simultaneous machining: 60% Turning: 80%



Z WA v								;	arcsec							
V				U-Rot					V-Rot					W-Rot		
X		1	1.5	3	60	600	1	1.5	3 [min]	60	600	1	1.5	3	60	600
	EA-91x DD	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0
	T1-91x915 TAP9	0	0	0	0	2	0	0	0	0	0	0	0	0	0	0
Positioning mode	T1-91x915 TAP9v	0	0	0	0	2	0	0	0	0	0	0	0	0	0	0
actival	T1-91x520 TAP5	-1	-2	-3	8	13	89	102	109	44	36	0	0	0	0	0
	T1-91x520 TAP5v	-1	-2	-3	8	13	89	102	109	44	36	0	0	0	0	0
E E	EA-91x DD	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0
	T1-91x915 TAP9	0	0	0	1	4	0	0	0	0	0	0	0	0	0	0
Simultaneous machining	T1-91x915 TAP9v	0	0	0	1	4	0	0	0	0	0	0	0	0	0	0
	T1-91x520 TAP5	-1	-2	-3	8	13	89	102	109	44	36	0	0	0	0	0
Managari Interessing	T1-91x520 TAP5v	-1	-2	-3	8	13	89	102	109	44	36	0	0	0	0	0
Printing and Print	EA-91x DD	0	0	1	1	0	-2	-2	-4	-8	-7	0	0	0	0	2
	T1-91x915 TAP9	0	0	0	-4	3	0	0	0	-1	0	0	0	0	0	0
Turning	T1-91x915 TAP9v	0	0	0	-4	3	0	0	0	-1	0	0	0	0	0	0
	T1-91x520 TAP5	-1	-2	-3	8	13	89	102	109	44	36	0	0	0	0	0
	T1-91x520 TAP5v	-1	-2	-3	8	13	89	102	109	44	36	0	0	0	0	0
	EA-91x DD	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0
Positioning mode T	T1-91x915 TAP9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	T1-91x520 TAP5	-2	-3	-3	-3	-3	102	110	100	91	88	0	0	0	0	0
TO THE RESERVE TO THE	T1-91x520 TAP5v	-2	-3	-3	-3	-3	102	110	100	91	88	0	0	0	0	0
	EA-91x DD	0	0	0	1	1	0	0	0	1	1	0	0	0	0	0
Simultaneous	T1-91x915 TAP9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
machining	T1-91x915 TAP9v	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
as as	T1-91x520 TAP5	-2	-3	-3	-3	-3	102	110	100	91	88	0	0	0	0	0
- E	T1-91x520 TAP5v	-2	-3	-3	-3	-3	102	110	100	91	88	0	0	0	0	0
	EA-91x DD	0	0	1	4	4	-2	-3	-5	-10	-10	0	0	0	-2	-2
The state of the s	T1-91x915 TAP9	0	0	0	-1	-1	0	0	0	0	0	0	0	0	0	0
	T1-91x915 TAP9v	0	0	0	-1	-1	0	0	0	0	0	0	0	0	0	0
TO 14 May 1 1 2 1 A	T1-91x520 TAP5	-2	-3	-3	-3	-3	102	110	100	91	88	0	0	0	0	0
	T1-91x520 TAP5v	-2	-3	-3	-3	-3	102	110	100	91	88	0	0	0	0	0
0 10	EA-91x DD	0	0	0	0 -1	0	0	0	0	0	0	0	0	0	0	0
Positioning mode	T1-91x915 TAP9	0	0	0		-1 -1	0	0	0		0	0	0		0	0
(aution)	T1-91x915 TAP9v	0		0	-1 2	-1 2	0	99	106	0	41	0		0		0
NA.	T1-91x520 TAP5 T1-91x520 TAP5v	-2 -2	-2 -2	-3 -3	3	2	87 87	99	106	45 45	41	0	0	0	0	0
- MCM	EA-91x DD	0	0	-3 0	0	0	0	0	0	45	0	0	0	0	0	0
	T1-91x915 TAP9	0	0	0	-1	-1	0	0	0	0	0	0	0	0	0	0
Simultaneous	T1-91x915 TAP9v	0	0	0	-1	-1	0	0	0	0	0	0	0	0	0	0
n machining	T1-91x915 TAP9V	-2	-2	-3	3	2	87	99	106	45	41	0	0	0	0	0
	T1-91x520 TAP5v	-2	-2	-3	3	2	87	99	106	45	41	0	0	0	0	0
	EA-91x DD	0	0	1	-2	-5	-2	-2	-4	-17	-23	0	0	0	2	5
	T1-91x915 TAP9	0	0	0	-2	-4	0	0	0	0	0	0	0	0	0	0
the strong and the st	T1-91x915 TAP9v	0	0	0	-2	-4	0	0	0	0	0	0	0	0	0	0
	T1-91x520 TAP5	-2	-2	-3	3	2	87	99	106	45	41	0	0	0	0	0
	T1-91x520 TAP5v	-2	-2	-3	3	2	87	99	106	45	41	0	0	0	0	0

The values for turning have been determined with the flux wea placement and rotation may be expected.

# **Duty cycle**Positioning mode: 20% Simultaneous machining: 60% Turning: 80%

Information regarding questions about cycle time, PLC, commissioning and application (spec. simultaneous operation)

### Cycle time calculation

pL has specific calculation tools at its disposal. Where necessary, we can provide assistance when calculating the piece part time. Based on your information, we will prepare a detailed cycle time calculation. See the table to the right for reference values for the clapping cycle.

	unclamp	clamp *
EA-913	90 ms	100 ms
EA-915	90 ms	100 ms
EA-918	90 ms	100 ms
EA-520	120 ms	150 ms

<sup>\*</sup> can be eliminated with PLC optimization

### **PLC** models

Spindle clamping is a pL LEHMANN exclusive and has great potential for savings. At www.lehmann-rotary-tables.com, you can find appropriate PLC templates.

### Parameter lists\*

A variety of parameter lists for various machines and three typical applications for each are available (Download).

Automatic parameter setting via CNC program. For example, available for FANUC ROBODRILL.

asttyp	Massentrag- heitsmoment		Kriterien (wern Massentragheitsmoment nicht bek Last Dimens	
	J	~	À	Ø
Catalog (Max.Speed)	< 0.8kgm^2	*	< 90kg	< 230mm
Usual At At	<1.2kgm*2	~	< 120kg	< 320mm
Max.Load	< 8kgm^2	*	< 800kg	< 460mm

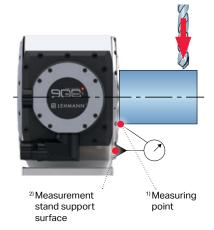
 $<sup>\</sup>mbox{^{\dag}}$  Tool for determining the permissible limit values for each rotary table; please contact us.

### **Stiffness**

Expected response (elasticity) to corresponding load:

Reference values	Unit	913	915	918	520	Remarks
Torsion, gear unit	Nm/°	-	-	-	5,400	in conjunction with feed torque
Spindle, axial*	kN/mm	700	700	700	2,400	in conjunction with axial force
Spindle, deflection*	kNm/mm	32	32	37	52	in conjunction with pull-out torque

<sup>\*</sup>All data measured at face of spindle  $^{1}$ , relative to rotary table housing  $^{2}$ ; spindle clamping active (inactive: axially approx. -20%, deflection approx. -50%)



#### 1 Maximum speeds

Maximum speeds are permissible only with standard moment of inertia, otherwise the time to standstill if the emergency OFF is tripped will be too long. In this case, the axis will spin without control or the clamping will break the rotating spindle.

#### 2 **Balancing**

To ensure fault-free and safe operation, it is essential that workpieces and their clamping devices do not exceed the maximum vibration values. The maximum vibration value at 2000 rpm is <0.5 mm/s by default.

The maximum permissible vibration value is 4.5 mm/s (recommended upper limit is 1.8 mm/s). By request, rotary tables including fixtures and workpieces can be checked and balanced at the factory or on site.

#### 3 Rotary table temperature

The motor temperature must not exceed 90 °C. Otherwise the rotary table's internal electronics may suffer permanent damage. Temperature monitoring via the control system is required. If 90 °C are to be exceeded during operation, active cooling for the rotary table is recommended. See p. 24

#### 4 Safety information

Machining can be performed at high speeds, so corresponding safety measures must be taken and observed!

All commonly applicable standards concerning the safety of machinery (in this case for lathes) must be observed at all

In particular, the following points must be observed:

- It must be prevented that the spindle starts moving when the work area door is open (reliably limited, reduced speed, accordingly).
- Ensure that in the case of an energy failure (air, hydraulics, power) no hazardous situation can occur (safe breaking of axes, workpiece remains clamped without energy, etc.).
- Ensure that safety-relevant parameters (speed with door open, etc.) cannot be manipulated by the user (password, key switch, etc.).
- Guards (housings) must be adjusted to meet the increased demands of turning operations.

### Requirements for safety cabs for spindle operation

(according to ISO 23125:2015)

•	J	•		
	max. perm. Ø	max. perm. speed	Sheet metal	Polycarbonate**
	<Ø 130	3'500 rpm *	2 mm	6 mm
	<Ø 260	2,700 rpm	2.5 mm	6 mm
	< Ø 500	1'400 rpm	2.5 mm	8 mm

The following rule of thumb may be applied: As long as workpieces and speeds are smaller or equal to the largest possible tool at the milling spindle, the requirements for guards are met.

Caution: When using rotary tables of type EA or T (with horizontal axis), the workpiece may spin off upwards – preventive measures are required for all machines without top cover or with bellows only.



<sup>\*</sup> higher speeds at smaller Ø upon request \*\* Caution, subject to aging, consider reduction factors

### Definition of the terms used in this catalog

#### 5 **Drive data**

The term «drive data» always refers to rotational speed, acceleration as well as jerk limitation.

#### 6 Gear unit

[Nm]

**Gear unit loading (M**<sub>gear max.</sub>) **[Nm]** ....refers to the maximum permissible mechanical torque at a spindle rotational speed of 1rpm.

### She torque (M feed)

...refers to the available torque at a rotational speed of 1 rpm, corresponding to the maximum permissible gear load. Depending on the motor used and/or duty cycle, however, it can be correspondingly lower.

### Eccentric spindle load (sl $_{\rm eccentric}$ ) [Nm]

The eccentric load catalog\* corresponds

- to 0 Nm (standard load always centric) for EA and M rotary tables as well as dividing/indexing axes of T-type rotary tables
- to the maximum torque for T-type rotary tables, which affects the swivelling/tilting axis in the form of the intrinsic load of the dividing/indexing axis as well as that of the cubic standard load. Please refer to the respective parameter list, catalog values.

For T-type rotary tables, the eccentric load usual\* is identical to the gear load with sls. For an EA rotary table, this torque is equal to the value resulting from the maximum eccentric load when using a rotoFIX Alu with a standard load. Please refer to the respective parameter list, usual values.

The eccentric load max load\* corresponds to the maximum mechanical torque which can still be transmitted without any damage using the gear unit at a minimum rotational speed of approx. 10 rpm. Please refer to the respective parameter list, max load values.

\* For definitions, please refer to «Geometry / Integration» **p. 51** 





Center of gravity shift without and with load. The greater the red center of gravity, the greater is the gear unit loading in the swivelling/ tilting axis. The blue arrow shows the direction in which the center of gravity moves from «without load» to «with load».

pL standard spindle load (sls = sl <sub>standard</sub>) pp. 34/35 [kg] ...refers to the pL spindle load defined as standard, derived from practice, covering approximately 90% of all applications. All drive data and parameter lists are designed for the cubic pL standard load. All masses moving within this volume (workpiece including device) and clamped coaxially to the rotary axis can be moved using the standard drive data. Eccentrically arranged standard pL spindle loads may require a reduction of the drive data.

### Standard moment of inertia (J $_{\mbox{\tiny standard}}$ ) p. 34/35

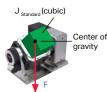
[kgm2]

...refers to the resulting moment of inertia due to the defined pL standard load and its shape, if the load is clamped coaxially to the rotary axis. The usual J ratio between load and motor is generally 1:1 or less (e.g. 0.5:1).

#### Max. perm. moment of inertia (J $_{\mbox{\tiny max}}$ ) [kgm2]

...corresponds to 10x the standard moment of inertia (J  $_{\text{standard}}$ ) In most applications, this moment of inertia is not exceeded even with large workpieces. It should also be noted that the J ratio of 10:1 is NOT exceeded with any motorized model. Large J values can be moved, of course, but required appropriate adjustments (on request).





STUB (static torque of unequal burden) [Nm]

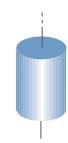


torque of unequal burden) [Nm]

### EA-913



m = 21 kg J = 0.07 kgm<sup>2</sup>



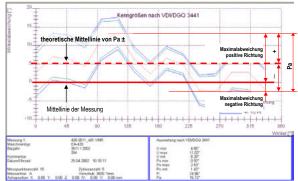
## Function explanations, limit values and conditions minimize your risks

#### 7 Rotary table accuracy

All accuracy data apply to an unloaded rotary table

### Measuring process

- 5 Warm-up cycles
- 5 Measuring cycles
- 24 Measuring points (15°)
- Acceleration 500°/s²
- Heidenhain ROD 800 measuring and test equipment with K15 coupling
- Unloaded rotary table as individual module room temperature approx.



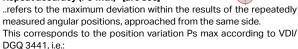
Explanation of indexing accuracy Pa ±:

### Indexing accuracy (Pa ±) [arc sec]

...refers to the sum of maximum positive and negative deviations between the ACTUAL position and the TARGET position of all angular positions over 360° measured in a direction of rotation, stated as ± value. This is equal to the position deviation Pa according to VDI/DGQ 3441, but accumulated (example: TG ± 15" corresponds to Pa 30") and:

- without consideration of the reversal error into account
- without consideration of the radial and axial run-out error of the

### Repeat accuracy (Ps with) [arc sec]

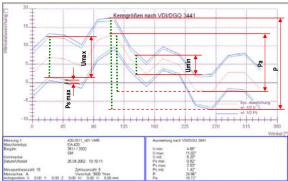


without consideration of the reversal error into account

### Positioning accuracy (P) [arc sec]

...refers to the maximum deviation between the TARGET position and the ACTUAL position when the direction of rotation changes. This corresponds to the positioning uncertainty P according to VDI/ DGQ, i.e.:

without consideration of the radial and axial run-out error of the spindle.



Explanation of various parameters according to VDI/DGQ 3441:

### Reversal backlash (U gear) [arc sec]

...refers to the maximum mechanical backlash when the direction of rotation changes within a specific number of repeatedly measured angular positions.

- This does not correspond to a measurement parameter according to VDI/DGQ 3441
- The elasticity of all parts connected in the drive train is NOT taken into account

### Reversal error (U average\*) [arc sec]

...refers to the average reversal error, including elasticity, backlash and/ or overshoot of all parts connected in the drive train when the direction of rotation changes within a specific number of repeatedly measured angular positions.

This corresponds to the reversal error U average according to VDI/ DGQ 3441. The average value is calculated on the basis of all mea-

\* For compensation and definition of backlash, please refer to «Geometry / Integration, 6.4»

### Definition of the terms used in this catalog

#### 8 Speed

### **Duty cycle (ED)**

...refers to the duration of the movement per unit of time according to the DIN/VDE 0530 Standard. The axis is designed for an operation of ED 40% at a cycle duration of 10 min. To protect the axis from overload, it is not permissible to operate the unit for more than 10 min without interruption and at speeds above 500 rpm. If these values are exceeded, signal 'Axis released' is reset, causing the spindle to stop. If longer continuous cycles at speeds above 500 rpm are required, contact us.

**DIN/VDE** 0530 S3, ED 40%

### Rotational spindle speed (n spi)

...always refers to the maximum possible rotational speed of the spindle

- while complying with the duty cycle ED
- with the corresponding motor
- with the pL standard spindle load (cubic)

### Cycle time 90° / 180° (t $_{90°}$ / t $_{180°}$ )

[sec]

[rpm]

...refers to the time required for the entire dividing / indexing operation for a 90°/180° movement



 Dividing/indexing operation OPTIMIZED = as standard, but the clamped signal is queried only prior to the feed movement. This operation requires adjustment of the respective machine PLC and is not included in the pL scope of



### Spindle bearing

[N]

..refers to the maximum permissible axial load on the spindle. It includes the workpiece, devices, machining forces and other forces resulting from the rotational and tilting movement.

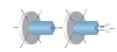
### Pull-out torque (M , ,,)

[Nm] ..refers to the maximum permissible tiling load on the spindle, measured from the spindle face. It includes the workpiece, devices, machining forces and torques resulting from the rotational and tilting movement.



...refers to the total, maximum permissible load which is installed starting from the spindle nose and performs a rotational movement together with the spindle (device and workpiece). This load does not correspond to the pL standard spindle load.

Radial and axial run-out (ro  $_{\rm con/ax}$ ) [mm] ...refers to the maximum deviation occurring in the axial (axial run--out) or radial (radial run--out) direction when measured over 360°. Measured in each case on the maximum possible diameter of the spindle nose.



#### 10 Clamping

### Clamping torque (M clamp)

...refers to the maximum permissible torque load on the spindle nose during active clamping (5 bar air pressure). The pL clamping is extremely rigid. Depending on the load, there is also a setting behavior in addition to a usual elasticity. We  $distinguish\ between\ three\ phases\ when\ progressing\ from\ zero\ load\ to\ maximum\ load.\ The\ setting\ behavior\ results\ in\ an$ irreversible torsion after unloading as follows:



- Phase 1 «normal» (approx. 1/3 to 1/2 of the permissible clamping torque) up to approx. 0.0015 mm\*
- Phase 2 «increased» (approx. 2/3 of the permissible clamping torque) up to approx. 0.002 0.004 mm\*
- Phase 3 «maximum» (up to 100% of the permissible clamping torque) up to approx. 0.008 mm\*

In practice, in order to be prepared for adverse factors such as vibration, dulled tools, etc., a maximum of 50% or the spindle clamping torque should be applied during the calculation phase of the application

\* For unilateral load, in relation to the spindle outside Ø of the respective rotary table. The indexing and repeat accuracy is not impaired by



## Function explanations, limit values and conditions minimize your risks

### Leaktightness (acc. to EN 60529)

...refers to the leaktightness in terms of protection against accidental contact, protection against the ingress of foreign matter and protection against the ingress of water:

IP 65: Protection against accidental contact, no ingress of dust, protection against the ingress of water jets

 $\textbf{IP 66:} \ \textbf{Same protection as IP 65, but protection against the ingress of powerful water jets}$ 

IP 67 (standard at pL): Same protection as IP 66, but protection against the ingress of water from temporary immersion

IP 68 (optional at pL): Same protection as IP 67, but protection against the ingress of water from permanent immersion



### Geometry and integration

All accuracy data apply to an unloaded rotary table

### Tilting drift (sd 200)

...refers to the deviation of the perpendicularity between the dividing/indexing axis and the swivelling/tilting axis over a specific tilting range. pL always measures three points: -90° (horizontal), -45° and 0° (vertical), always related to the position of the dividing/indexing axis and on a radius starting from the center of the swivelling/tilting axis of 200 mm.

### Offset values (offset)

...refer to the deviation from any theoretical NOMINAL values in order to ensure easier alignment of the rotary table on the machine and faster commissioning.

### Pitch error (pe)

...refers to the effective NOMINAL-ACTUAL deviation over a specific rotation angle ("pitch error") for axis error compensation on the CNC machine. For rotary tables with gear unit, this occurs typically with the movement of eccentrically arranged loads such as clamping yokes, swivelling/tilting axes etc.

### Backlash (bl)

...refers to the mechanical and electronic reversal error\* (gear unit, angular position measuring system, positioning control...) for the loose backlash compensation on the CNC machine.

\* For definition see «Rotary table accuracy» p. 49

### Parameter lists

To minimize commissioning time and make maximum use of the pL rotary table, you can find parameter lists for various controls at www.lehmann-rotary-tables.com. In the case of load-relevant parameters, we distinguish between...

...refers to the practice-oriented drive values for pL standard spindle loads, which should usually be set (pL recommendation) in order to still provide certain reserves to integrate deviations occurring in practice and to allow an easier control comparison. Normally, no warm-up is required here.

### catalog

...refers to the maximum achievable catalog drive values for pL standard spindle loads, for which more demanding requirements are imposed both on the commissioning engineer and on the material in order to achieve these values. Depending on the respective application, they must be reduced (empirically). A warm-up cycle is frequently recommended

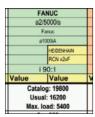
### max load

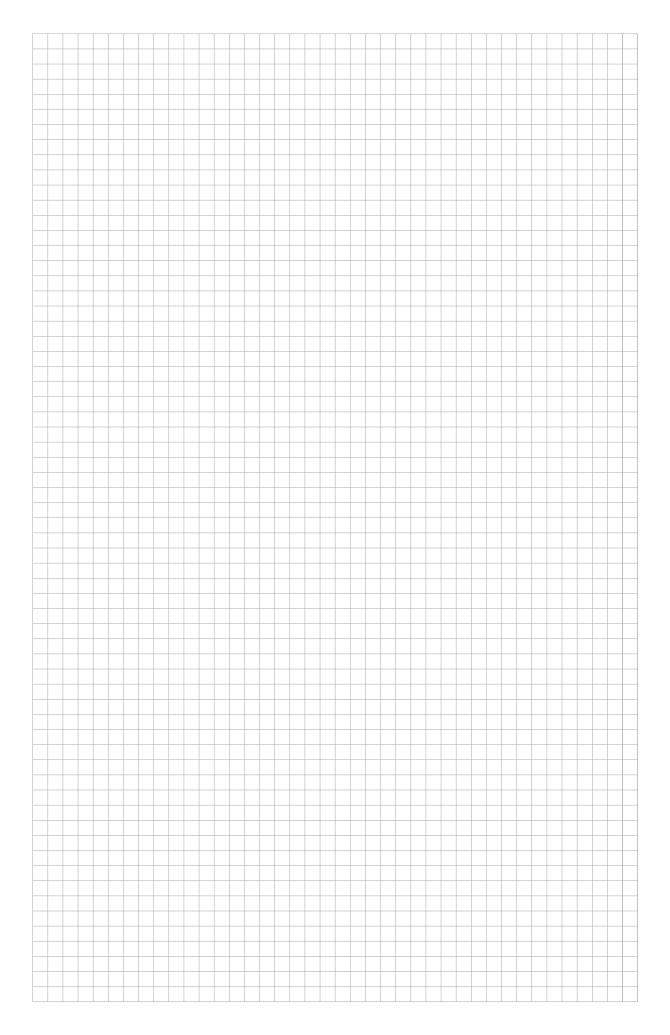
...refers to the maximum achievable drive values for J max. and eccentric loading.



offset 1: [mm] 0.013

pitch-error: [°] 0.005



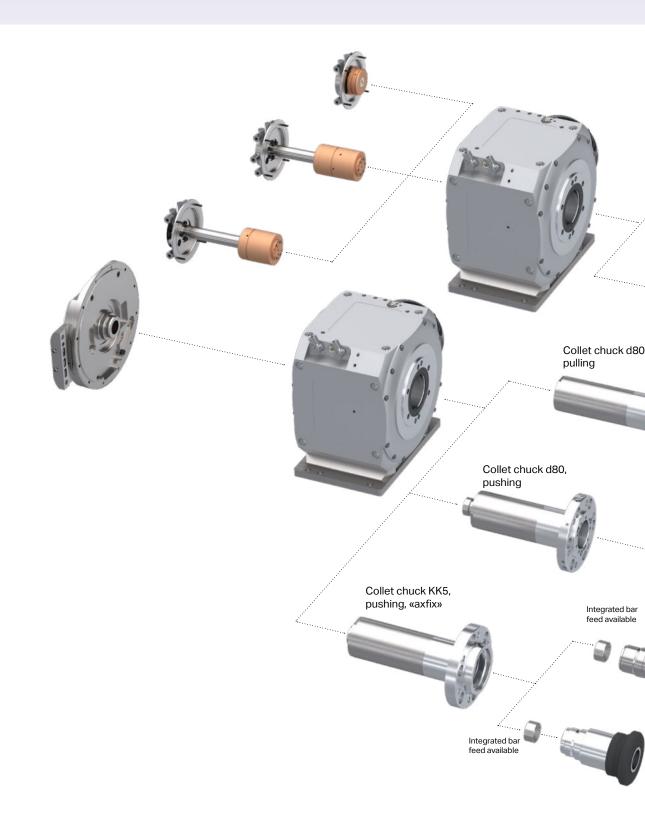


## Workpiece clamping systems

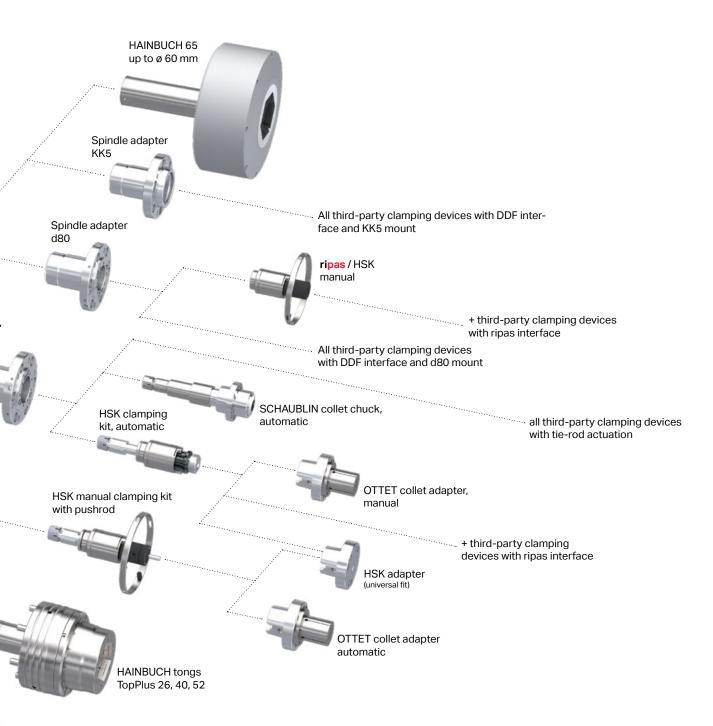
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10 mg			



To ensure production reliability: powerless workpiece clamping, keeping the workpiece in place even in the event of pressure loss

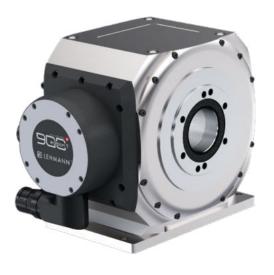






F35

A multitude of accessories adaptable thanks to standardized interface



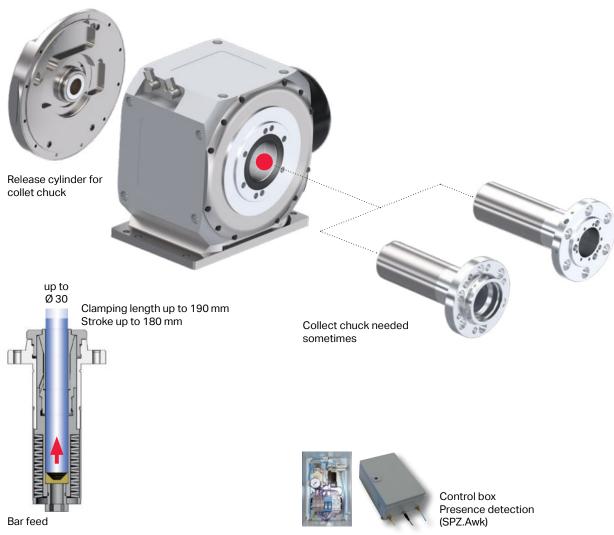






Item no.	Designation	Dimensions
SPI.91x-d80	Spindle adapter	Outer diameter 80 mm
SPI.91x-KK5	Spindle adapter bigBore with KK5	

Clamped even without power and pressure: The safe solution for workpiece clamping when operating at high speeds



Item no.	Designation	Dimensions	can be retrofitted
SPZ.91x-s3	Collet chuck d80 incl. release cylinder	pushing, stroke: 3.0 mm	
SPZ.91x-s9	Collet chuck d80 incl. release cylinder	pushing, stroke: 9.0 mm	
SPZ.91x-s9d30	Collet chuck KK5 incl. release cylinder	pushing, stroke: 9.0 mm, effective passage increased Ø 30 mm	
SPZ.91x-z3	Collet chuck d80 incl. release cylinder	pulling, stroke: 3.0 mm, M24x1.5	
SPZ.91x-z9	Collet chuck d80, incl. release cylinder	pulling, stroke: 9.0 mm, M24x1.5	
SPZ.91x-Stange	Bar feed ø30, stroke 140 mm	fits SPZ.91x-s9d30	•
SPZ.91x-Stange28	Bar feed ø28, stroke 180 mm	fits SPZ.91x-s9d30	•

collet chucks for EA-918 require option SPZ.918-ada

### Options for all sizes

SPZ.Awk-Vor	Preparation for presence check only possible for automatic clamping (only with adapter from pL)
SPZ.Awk	Control fox for presence check

cannot be combined with bar feed

HSK clamping with precise angular positioning = compact palletizing system manually and automatically



newChuck: ideal table chuck for machining of the 5th or 6th side, for example, with integrated

### The main advantages of ripas

- Very space-saving, as integrated completely in the spindle
- Easy to retrofit
- Very torsionally rigid
- High precision
- Standard interface proven in thousands of applications
- When required, standard adapter can also be used (no rough positioning possible)

### The principle

The basis is the standardized HSK clamping with conventional clamping sets. However, the carrier cams are precisely ground and can deflect axially. The counterpart (HSK adapter) has a precise groove as well as a positioning bore for the guide pin.

### The function

ripas has 3 functions:

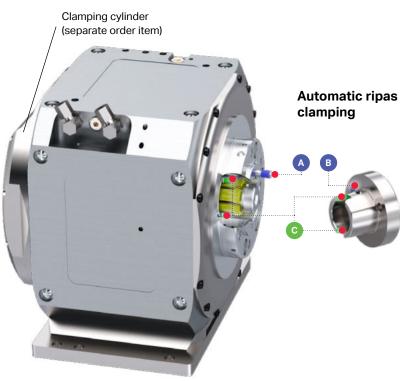
- Anti-twist protection
- Rough positioning
- Precision positioning

### **Process**

During changes (manually or automatic), the guide pin A ensures proper orientation while providing rough positioning at the same time 19.

Shortly before the face is reached, the inner precision cams perform the precision positioning ©.





Item no.	Designation	Weight [kg]	Manual (MAPAL)	Pneumatic	Required clamping cylinder
RIP.91x-63m	ripas clamping, manual, A63		•		
RIP.91x-63p	ripas clamping, pneumatic, A63			•	SPZ.91x-z9
RIP.91x-63m-OT	ripas clamping adapter for collet chuck, A63, manual (Ottet)		•		
RIP.63ada	ripas adapter, A63				RIP.91x-63m or RIP.91x-63p
RIP.63-KD-1	Alignment pin, A63				

Above dimensions apply with ripas adapter inserted. Without adapter, the clamping kit protrudes approx. 10.5 mm.

HSK = Hollow shank taper to DIN 69063-1 (spindle) or DIN 69893 (adapters)

Technical data for ripas / HSK		HSK-A63 manual		HSK-A63	automatic
	Unit	Standard	ripasGrip (option)	Standard	ripasGrip (option)
Perm. tension, max.	kN	-		10 at 50 bar 1)	
Resulting insertion force on adapter, max.	kN	30 at 2	20 Nm <sup>2)</sup>	3	30
Perm. pull-out torque (before losing face contact)	kN	appro	x. 600	appro	ox. 600
Transport load	kg	appro	ox. 60	appr	ox. 60
Perm. torque 3) (slip 4) max. ± 0.003°) A	Nm	-	approx. +50%	approx. 150	approx. 300
Perm. torque 3) (slip 4) max. ± 0.01°) B	Nm	-	approx. +50%	approx. 250	approx. 450
Repeat accuracy, XYZ	mm	< 0.	.005	< 0	.005
Repeat accuracy, angular	± arc sec		8		4

<sup>1)</sup> with SPZ.91x-z9

### Options for all sizes

SPZ.Awk-Vor	Preparation for presence check only possible for automatic clamping (only with adapter from pL)
SPZ.Awk	Control box for presence check (see p. 57)

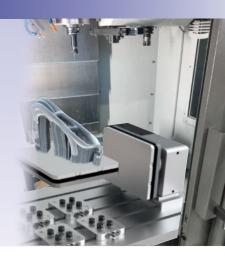
<sup>&</sup>lt;sup>3)</sup> Values apply under static conditions, without any vibrations, with no load, dry, free of grease, clean

<sup>2)</sup> Radial screw

<sup>4)</sup> returns to original position after unclamping/clamping

## Tooling for individual finish machining / finishing





### **QUATTRO** chuck

Connection for location check/ cleaning

Manual clamping: 180° turn suffices

Compressed air connection for clamping (continuous pressure or pulsed). Mechanically locked in the event of pressure drop (safety).

Dimensions: 150 x 150 x 34 mm (L x W x H)

6 bolts (M10) for fastening to the machine table, 100 or 50 mm pattern

### **UNO chuck**



UNO chuck Ø 100 with 4 fastening holes (M8) in a 50 mm spacing

### 6 benefits (applies to QUATTRO and UNO)

- only 34 mm high
- manual and pneumatic in one
- easy to clean
- pressureless clamping
- easy mounting
- maintenance-free

### Technical data

		UNO	QUATTRO
Repeat accuracy		approx. ± 0.005 mm	
Data-Man famous alamost	Manual	approx. 6 kN	approx. 24 kN
Retention force, clamped	pneumatic at 6 bar	approx. 10 kN	approx. 40 kN

all values tentative data

### Item no.

Item no.	Designation	Dimensions	Weight [kg]	max. speed [rpm]
AML.SPF-U	UNO chuck	Ø50x34 mm, 1 pin	2	
AML.SPF-Q	QUATTRO chuck	150x150x34 mm, 4 pins	5	on request

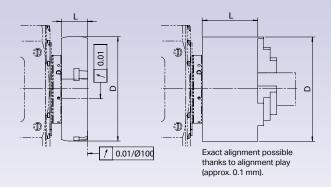


for more information, see AM-LOCK brochure



## Clamped quickly and easily

## Quickly converted for small series and express work



### Faceplates (axial discs)

	Item no.	Designation	Diameter D [mm]	Thickness [mm]	Passage [mm]	L from spindle [mm]	Weight [kg]	max. speed [rpm]	Moment of inertia J [kgm²]
	TPL.91x-250	Faceplate, 8 T-slots 14 mm	250	45	45	42.1	17	*	0.14
91×	TPL.91x-300**	Faceplate, 8 T-slots 14 mm	300	50	45	47.1	27	*	0.31
	TPL.91x-350**	Faceplate, 8 T-slots 14 mm	350	50	45	47.1	37	*	0.58
	TPL.5xx-GEN	Increased accuracy = 1/2 tolerance va	lues						
	TPL.mon	Faceplate assembled and measured							



### Scroll chucks, steel (manual)

 $incl.\ matching\ adapter\ flange,\ 1\ set\ each\ of\ hard\ boring\ and\ turning\ jaws\ as\ well\ as\ clamping\ wrench\ and\ fastening\ screw$ 

	Item no.	Designation	Diameter D [mm]	Thickness [mm]	Passage [mm]	L from spindle [mm]	Weight [kg]	max. speed [rpm]	Moment of inertia J [kgm²]	Moment of inertia J [kgm²]
	BFU.91x-160ps	Scroll chuck	160		42	85	13		0.04	520-160ps
91×	BFU.91x-200ps	Scroll chuck	200		55	95	23		0.12	520-200ps
	BFU.91x-250ps	Scroll chuck	250		76	106	39		0.31	520-250ps
	BFU.5xx-GEN	Increased accuracy = 1/2 tolerance values								



Further information: www.niederhauser.ch Request installation and operating instructions directly from manufacturer

### Wedge bar chuck SMW type HG-F

(manual, modular helical gear jaw system)

incl. matching adapter flange, 1 set of hard, reversible ground stepped jaws in the chuck as well as clamping wrench and fastening screw

	Item no.	Designation	Diameter D [mm]	Thickness [mm]	Passage [mm]	L from spindle [mm]	Weight [kg]	max. speed [rpm]	Moment of inertia J [kgm²]	Moment of inertia J [kgm²]
	BFU.91x-160ks	Wedge bar chuck	160		46	70	11		0.04	520-160ks
91×	BFU.91x-200ks	Wedge bar chuck	210		60	92	22		0.11	520-200ks
	BFU.91x-250ks	Wedge bar chuck	260		81	110	38		0.30	520-250ks
	BFU.5xx-GEN	Increased accuracy = 1/2 tolerance va	alues							



**Further information:** www.smw-autoblok.de and www.niederhauser.ch Request installation and operating instructions directly from manufacturer

 $<sup>\</sup>mbox{\ensuremath{^{\star}}}$  = TPL without assembly permits full speed, assembly to be performed by client

<sup>\*\*</sup> Increased center height required

Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation	Size [mm]	L from spindle (without jaws)	Pneumatic	Manual	Centered	Fixed jaw	Jaw stroke [mm]	Clamping force [kN] *	Max. pressure (bar)	Max. torque [Nm]	Max. range with standard jaws ** [mm]	Weight [kg]	Max. speed *** [rpm]	Required rotary union ***	SCHUNK catalog reference	SCHUNK Item no. incl. adap- ter flange
	SCH.510-KSP64	KSP-Z plus 64	64 x 64	65.7	•			•	2	4.5	9		40		100	DDF.91x-04-d80	0405102	40105124
	SCH.510-KSP100	KSP-Z plus 100	100 x 100	80.2	•		•		2	18	9		70		100	DDF.91x-04-d80	0405202	40106193
	SCH.510-KSP100LH	KSP-LH-Z plus 100	100 x 100	80.2	•			•	6	8	9		70		100	DDF.91x-04-d80	0405222	40106253
	SCH.510-KSP100F	KSP-F-Z plus 100	100 x 100	80.2	•			•	4	18	9		70		100	DDF.91x-04-d80	0405212	40106195
	SCH.510-KSA100	KSA-Z plus 100	100 x 100	85.2		•	•		2	18	9	8	70		100		0405291	40106194
	SCH.510-KSA100LH	KSA-LH-Z plus 100	100 x 100	85.2		•	•		6	18	9	20	70		100		0405295	40106196
980	SCH.510-KSA100F	KSA-F-Z plus 100	100 x 100	85.2		•		•	4	18	9	8	70		100		0405293	40106197
	SCH.510-KSP160	KSP-Z plus 160	160 x 160	102.7	•		•		3	45	9		120	15.80	100	DDF.91x-04-d80	0405302	40101546
	SCH.510-KSP160LH	KSP-LH-Z plus 160	160 x 160	102.7	•		•		8	20	9		120	16.00	100	DDF.91x-04-d80	0405322	40101547
	SCH.510-KSP160F	KSP-F-Z plus 160	160 x 160	102.7	•			•	6	45	9		120	15.80	100	DDF.91x-04-d80	0405312	40101548
	SCH.510-KSA160	KSA-Z plus 160	160 x 160	107.7		•	•		3	45	9	10	120	15.80	100		0405391	40101549
	SCH.510-KSA160LH	KSA-LH-Z plus 160	160 x 160	107.7		•	•		8	45	9	25	120	15.80	100		0405395	40101550
	SCH.510-KSA160F	KSA-F-Z plus 160	160 x 160	107.7		•		•	6	45	9	10	120	15.80	100		0405393	40101551
	SCH.520-KSP250	KSP-Z plus 250	250 x 250	128.2	•		•		5	55	6		170	50.00	100	DDF.91x-04-KK5	0405502	40101552
KK5	SCH.520-KSP250LH	KSP-LH-Z plus 250	250 x 250	128.2	•		•		15	20	6		170	50.00	100	DDF.91x-04-KK5	0405522	40101553
	SCH.520-KSP250F	KSP-F-Z plus 250	250 x 250	128.2	•			•	10	55	6		170	50.00	100	DDF.91x-04-KK5	0405512	40101554



KSPZ plus 250 on EA-91x



SCHUNK-clamping unit on SCHUNK VERO-S (p. 63)

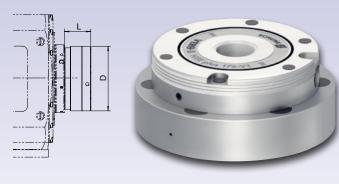
System & iBox

<sup>\*</sup> at max. pressure and / or max. torque
\*\* with standard jaws KTR 64 / 100 / 160 / 250 (processing must be carried out by the customer)
\*\*\* see p. 25, matching spindle adapter (p. 56) included in order item
\*\*\*\* only indexing allowed

Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

Further information: www.schunk.com

Request installation and operating instructions directly from manufacturer



	pL LEHMANN Item no.	Designation non-rusting	Pneumatic 6 bar	Turbo function	non-rusting	D [mm]	L from spindle [mm]	Draw-in force [kN]	Increased draw-in force with turbo function [kN]	Max. retention force [kN]	Weight [kg]	Max. speed ** [rpm]	Open	Anti-twist protection	Required rotary union*	SCHUNK catalog reference	SCHUNK item no. incl. adapter flange
d80	SCH.510-90ix	VERO-S NSE mini 90-V1	•	•	•	ø90	35	0.5	15	25		100	•	•	DDF.91x-04-d80	0435105	40105125
KK5	SCH.520-138ix	VERO-S NSE3 138-V1	•	•	•	ø138	79	7.5	28	75		100	•	•	DDF.91x-04-KK5	1313723	40105132
춫	SCH.520-176ix	VERO-S NSE plus 176-V1	•	•	•	ø176	90	9	40	75	12.00	100	•	•	DDF.91x-04-KK5	0471096	40101346

<sup>\*</sup> see p. 25, matching spindle adapter (p. 56) included in order item

Increased accuracy = 1/2 tolerance values; Item no. NPS.5xx-GEN

### Important technical data

	Unit	NSE3 138	NSE +176
Pneumatic system	[mm]	Yes	Yes
Repeat accuracy	[mm]	< 0.005	< 0.005
Actuating pressure	[bar]	6	6
Draw-in force	[kN]	28	40
Retention force M16	[kN]	75	75



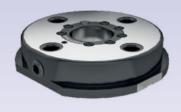






<sup>\*\*</sup> only indexing allowed







\* Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

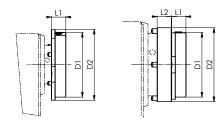
Further information: www.gressel.ch

Request installation and operating instructions directly from manufacturer

### **GRESSEL** gredoc pallet system

	pL LEHMANN Item no.	Designation	Manual	D1 [mm]	D2 [mm]	L1 [mm]	L2 [mm]	Weight [kg]	max. speed	spindle	GRESSEL Item no. incl. adapter flange
KK5	GRE.520-GRU*	gredoc round	•	ø135	154	30	30	6.4		SPI.91x-KK5	NGS.010.007.01

Technical data	Unit	Dimensions
Mechanical system		Yes
Repeat accuracy	(mm)	< 0.01
Draw-in force	(kN)	20
Height tolerance	(mm)	± 0.005



### Clamping devices for above GRESSEL gredoc pallet system

pL LEHMANN Item no.	Designation	Manual	D [mm]	L from spindle [mm]	Pallet sizes [mm]	Workpiece weight (perm.) [kg]	Weight [kg]	max. speed [rpm]	GRESSEL catalog reference	Base body required
GRE.SOL-40	solinos 40-4V-IT	•	148 x 135 x 135	198		8			KLM.040.020.01	
GRE.SOL-65	solinos 65-4V-IT	•	193 x 164 x 164	243		18.5			KLM.065.020.01	
GRE.C165-grip	C1 65 grip	•	178 x 65 x 67	117		2.9			CGM.065.001.01	
GRE.C165-präz	C1 65 precision	•	178 x 65 x 67	117		2.9			CGM.065.002.01	
GRE.C280-grip	C2 80 with reversible jaw grip	•	157 x 80 x 78	128		4			CGM.080.001.01	GRE.5xx-GRU
GRE.C2125-grip	C2 125 L-160 with reversible jaw grip	•	208 x 125 x 83	133		8.7			CGM.125.001.01	
GRE.SPZ	gredoc collect chuck	•	ø148 x 47.5	97.5	ø148	1.5			NGS.010.030.01	
GRE.LP	empty pallet	•	ø148 x 30	80	ø148	2.0			NGA.000.002.01	
GRE.LRP	Pallet with hole grid	•	ø148 x 30	80	ø148	2.0			NGA.000.003.01	
GRE.AB	Mounting pin, incl. fastening screw	•	ø40			0.1			NGA.000.001.01	

All items must be ordered separately! (Example of Lehmann EA-507: NGS.010.015.01 + CGM.080.001.01 + NGA.000.001.01)

### Possible applications











centrinos 65





EA application



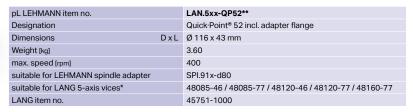
\*\* Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

Further information: www.lang-technik.de
Request installation and operating instructions directly from manufacturer

### LANG zero point clamping system







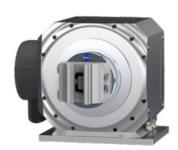




pL LEHMANN item no.		LAN.5xx-QP96**
Designation		Quick·Point® 96 incl. adapter flange
Dimensions	DxL	Ø 196 x 37 mm
Weight [kg]		
max. speed [rpm]		
suitable for LEHMANN spindle adapter		SPI.91x-d80
suitable for LANG 5-axis vices*		48155-77 / 48155-125
LANG item no.		45820-1000

<sup>\*</sup> The maximum length of the vice base body depends on the rotary axis type. Longer vice variants may be possible. Please inquire.

### Vices suitable for the LANG zero point clamping system



Example of application Makro-Grip® 77 with Quick-Point® 52 on LEHMANN EA-915

pL LEHMANN Item no.	Designation	Clamping capacity [mm]	Weight [kg]	Max. speed [rpm]	LANG Item no.	Base body required
LAN.MG46-S85	Makro·Grip® 46, length 102 mm Jaw width 46 mm	0-85			48085-46	
LAN.MG46-S120	Makro·Grip® 46, length 130 mm Jaw width 46 mm	0-120			48120-46	pL LEHMANN Item no. LAN.5xx-QP52
LAN.MG77-S85	Makro·Grip® 77, length 102 mm Jaw width 77 mm	0-85	2.30	400	48085-77	or
LAN.MG77-S120	Makro·Grip® 77, length 130 mm Jaw width 77 mm	0 – 120	2.90	400	48120-77	LANG Item no. <b>45751-1000</b>
LAN.MG77-S160	Makro·Grip <sup>®</sup> 77, length 170 mm Jaw width 77 mm	0 – 160	3.50	400	48160-77	
LAN.MG77-S155	Makro·Grip® 77, length 160 mm Jaw width 77 mm	0 – 155			48155-77	pL LEHMANN Item no. LAN.5xx-QP96
LAN.MG125-S155	Makro-Grip® 125, length 160 mm Jaw width 125 mm	0 – 155	8.40	400	48155-125	LANG Item no. <b>45820-1000</b>

All LANG vices can also be attached to other zero point clamping systems (Erowa, Schunk, 3R, etc.) after being adjusted slightly. For further information, please contact your local LANG Technik representative.

ER-036802 ER-073457

ER-115254 ER-073460

ER-073461

ER-032964

18 ER-032388 ER-073462

4

8.7

16.6

### Further information: www.erowa.com

ERO.5xx-MTS

ERO.520-P210

ERO.520-PC

Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation (incl. flange)	Manual	Pneumatic	D [mm]	L from spindle [mm]	Pallet sizes [mm]	Workpiece weight (perm.) [kg]	Weight  kg]	Max. speed [rpm]	Open	Clean Z-support	Rotary union	Chuck weight (incl. adapter flange) <sup>[kg]</sup>	EROWA Catalog Reference	EROWA Item no. incl. adapter flange
	ERO.5xx-FTSix	FTS Chuck (Inox)		•	ø74	46.5	ø72	4	1.50	4,000	•	•	1)	1.5	ER-057335	ER-073469
980	ERO.5xx-QCix	QuickChuck 100 P (Inox)	•		ø100	50	□50/ø148	35	2.60	3,000				2.6	ER-036345	ER-073351
쁑	ERO.5xx-ITS100ix	ITS Chuck 100 P (Inox)		•	ø100	50	□50/ø148	35	2.50	5,000	•	•	1)	2.5	ER-043123	ER-073433

ø148

□50/ø148

ø210

ø130

ø150

• ø210 98

• ø81/ø210

60

75

98

D

Increased accuracy = ½ tolerance values; Item no. NPS.5xx-GEN

ERO.520-P210c Product.Chuck 210 Combi

PowerChuck P

MTS IntegralChuck S-P/A

ProductionChuck 210

for all automatic chucks	;	
ERO.HSV	Manual control valve	supplied loose with all necessary cables and hoses, ready to connect
ERO.ASV-2	Automatic control valve	supplied loose, for installation in the control cabinet, with all necessary cables/hoses

Additionally required rotary union (see **p. 25**): 1) = DDF.91x-04-d80, 2) = DDF.91x-04-KK5

When standard pallets with open holes are used, water, metal chips etc. can get into the pallet chuck, air lines and control valve. To prevent this, seal kits are available from the respective chuck manufacturers.



FTS Chuck (Inox) ER-057335



ITS Chuck 100 P (Inox) ER-043123



50 4.00 4,500 • • 1)

50 8.70 5,000 ● ● 2)

120 16.60 4,500 • • 2)

□50/ø210 120 18.00 4,500 • • 2)

MTS IntegralChuck S-P/A ER-036802



PowerChuck P ER-115254



ProductionChuck 210 Combi ER-032388

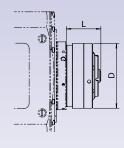


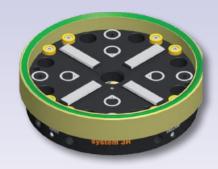
Manual control valve (option)

# system 3R

Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

Further information: www.system3r.com Request installation and operating instructions directly from manufacturer





	pL LEHMANN Item no.	Designation (incl. flange)	Pneumatic	D [mm]	L from spindle [mm]	Pallet sizes [mm]	Workpiece weight (perm.) [kg]	Weight [kg]	Max. speed [rpm]	Open	Clean Z-support	Clean cams	incr. clamp force/venting	Rotary union	SYSTEM 3R Catalog Reference	SYSTEM 3R item no. incl. adapter flange
	S3R.5xx-G70	3R GPS 70	•	ø99	56	ø70	10	2.70	5,450	•	•			1)	C198700	X663000
88	S3R.510-MGC*	3R Magnum Chuck	•	ø162	60	ø156, with index pin	100	7.70	5,450	•	•		•	1)	3R-SP26712	90940.12
	S3R.510-MCC	3R Macro Chuck	•	ø100	63	54x54, 70x70	10	3.50	5,450	•	•		•	1)	3R-600.14-30	90940.11
	S3R.520-G120	3R GPS 120	•	ø118	70	ø120	20	5.00	5,450	•	•			2)	C188770	X663020
KK5	S3R.520-G240	3R GPS 240	•	240x240	84	240x240	100	20.70	1,500	•	•	•	•	2)	C219200	X663030
	S3R.520-G240ix	3R GPS 240, rust-resistant	•	240x240	84	240x240	100	21.00	1,500	•	•	•	•	2)	X607620	X663040
te	S3R.RP-GPS240	Reference pallet GPS 240													C846600	
Palette	S3R.RP-GPS70120	Reference pallet GPS 70													C846360	
Ref. P	S3R.RP-Macro	Reference pallet Macro													36-606.1	
8	S3R.RP-Magnum	Reference pallet Magnum													3R-686.1-HD	

Additionally required rotary union (see **p. 25**): 1) = DDF.91x-04-d80, 2) = DDF.91x-04-KK5

\* For Magnum pallets only. Macro pallets may not be clamped

When standard pallets with open holes are used, water, metal chips etc. can get into the pallet chuck, air lines and control valve. To prevent this, seal kits are available from the respective chuck manufacturers.

Increased accuracy = 1/2 tolerance values; Item no. NPS.5xx-GEN



GPS 70



GPS 120



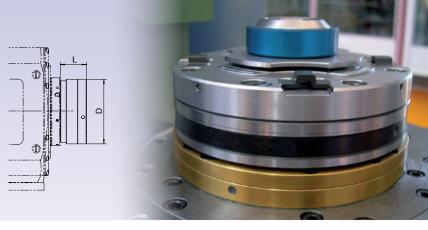


GPS 240

Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

Further information: www.parotec.ch

Request installation and operating instructions directly from manufacturer



	pL LEHMANN Item no.	PAROTEC catalog reference	Manual	Pneumatic	Hydraulic	D [mm]	L from spindle [mm]	Pallet sizes [mm]	Workpiece weight (perm.) [kg]	Weight  kgl	Max. speed [rpm]	Open [bar]	Clean Z-support	With re-tightening	Required rotary union*	PAROTEC Item no. incl. adapter flange
	PAR.5xx-PGmp6	POWER GRIP 160	•			ø145	56	□158	50			6				PT1160102710
	PAR.5xx-PGp6	POWER GRIP 160		•		ø145	56	□158	50			6	•	•	DDF.91x-04-d80	PT 1160142710
88	PAR.5xx-PYmp130	POLY GRIP	•			ø130	55	ø70-148	30			6		0		PT9911020710
	PAR.5xx-PYp110	POLY GRIP		•		ø110	55	ø70-148	50			6	•	•	DDF.91x-04-d80	PT9911320710
	PAR.5xx-DGp142 DEFO GRIP 100 ● Ø142 55 Ø100-148 20 6 ● DDF.91x-04-d80 PT6101032710															
* S6	see <b>p. 25</b> , matching spindle adapter ( <b>p. 56</b> ) included in order item o = optional															

<sup>\*</sup> see p. 25, matching spindle adapter (p. 56) included in order item

Increased accuracy =  $\frac{1}{2}$  tolerance values; Item no. NPS.5xx-GEN

Technical data	Unit	POWER GRIP	POLY GRIP	DEFO GRIP
Repeat accuracy	(mm)	+/- 0.002	+/- 0.002	+/- 0.005
Retention force without re-tightening	(kN)	17*	7	0.75
Retention force with re-tightening	(kN)	30*	12	1.2

<sup>\*</sup> For POWER GRIP 160-2 and 160-4 = Value x2 and x4, resp.

Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)



Increased accuracy =  $\frac{1}{2}$  tolerance values; Item no. NPS.5xx-GEN

Request installation and operating instructions directly from manufacturer

Further information: www.stark-inc.com

	pL LEHMANN Item no.	Designation	Hydraulic	D [mm]	L from spindle [mm]	Max. pull-out torque (Nm)	Open [bar]	Weight [kg]	Max. speed [rpm]	Suspension mechanism	Manual loading	Can be automated	X-Y-Z positioning/clean support	Z-contact check	Clamping check	Integrated media passage	Increased clamping force	Required rotary union*	STARK catalog refe- rence	STARK item no. incl. adapter flange
	STA.510-01		•	ø250	60	1740	40			•	•							-	804 331	SL1-63-0-0-2-01
	STA.510-02		•	ø250	60	2620	80			•	•						•	-	804 348	SL1-63-0-0-3-01
	STA.510-03	SVP 510 SPEEDY	•	ø250	60	1740	40			•	•					•		DDF.91x-04-d80	804 331	SL1-63-0-1-2-01
	STA.510-04	classic 1	•	ø250	60	2620	80			•	•					•	•	DDF.91x-04-d80	804 348	SL1-63-0-1-3-01
980	STA.510-05		•	ø250	60	1740	40			•	•				•			DDF.91x-04-d80	804 331	SL1-63-1-1-2-01
쁑	STA.510-06		•	ø250	60	2620	80			•	•				•		•	DDF.91x-04-d80	804 348	SL1-63-1-1-3-01
	STA.510-21		•	ø250	63	1740	40			•	•	•	•	•				DDF.91x-04-d80	804 500	SL1-63-0-1-2-11
	STA.510-22	SVP 510 SPEEDY	•	ø250	63	2620	80			•	•	•	•	•			•	DDF.91x-04-d80	804 501	SL1-63-0-1-3-11
	STA.510-23	classic 1 Twister	•	ø250	63	1740	40			•	•	•	•	•	•			DDF.91x-04-d80	804 500	SL1-63-1-1-2-11
	STA.510-24		•	ø250	63	2620	80			•	•	•	•	•	•		•	DDF.91x-04-d80	804 501	SL1-63-1-1-3-11

 $<sup>^{\</sup>star}\,\text{see}$  p. 25, matching spindle adapter (p. 56) included in order item

### Note permissible pull-out torque (use counter bearing if necessary)

Version 20 kN			Version 30 kN		
Distance [mm]	Force [kN]	Weight [kg]	Distance [mm]	Force [kN]	Weight [kg]
200	8.8	897	200	13.1	1335
300	5.9	601	300	8.8	897
400	4.4	449	400	6.6	673
500	3.5	357	500	5.3	540
600	2.9	296	600	4.4	449





Further information: www.amf.de

Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation	Pneumatic, 5 bar	Hydraulic, 50 bar	D [mm]	L from spindle [mm]	Weight [kg]	Max. speed [rpm]	Draw-in and closing force up to	Retention force	Indexing	Contact check	Required rotary union*	AMF catalog reference	AMF item no. incl. adapter flange
989	AMF.510-6206-S1	6206ILA-10	•		ø112	47			10 kN	25 kN	•	•	DDF.91x-04-d80	428771	533216
KK5	AMF.520-6206-S1	6206ILA-20	•		ø138	90			17 kN	55 kN	•	•	DDF.91x-04-KK5	428797	533232

 $<sup>^{\</sup>star}$  see  $\mathbf{p.}$  25, matching spindle adapter (p. 56) included in order item



AMF zero point clamping system



### Further information: http://fr.yerlymecanique.ch/

Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation	Pneumatic	D [mm]	fro	Workpiece size, approx. [mm]	Weight [kg]	max. speed [rpm]	Required spindle adapter	Required rotary union**	YERLY Catalog Reference	YERLY item no. incl. adapter flange
	YER.510-060P-*	YERLY* NPS 60	•	60	85	0.160				DDF.91x-04-d80	MD-60-*	YER.510-60P-*-JT
88	YER.510-100P-*	YERLY* NPS 100	•	100	108	0.1100				DDF.91x-04-d80	MD-100-*	YER.510-100P-*-TI
	YER.510-100M-*	YERLY* NPS 100	•	100	85	0.1100			SPI.91x-d80		MD-100-*	YER.510-100M-*-TI

<sup>\* 2 = 2-</sup>jaw chuck, 3 = 3-jaw chuck, 4 = 4-jaw chuck

### Yerly Basis 60P



## Yerly Basis 100P



### Yerly Basis 100M







Examples of YERLY chuck attachments. Can be adapted to any chuck type



System & iBox

AGG, DDF, RST, LOZ KAB, CNC, WMS

 $<sup>^{\</sup>star\star}$  see p. 25, matching spindle adapter (p. 56) included in order item





**Further information: www.evard-precision.ch**Request installation and operating instructions directly from manufacturer

### Centering vice - Type CM

pL LEHMANN Item no.	Designation	Size	Clamping capacity [mm]	Weight [kg]	Required accessories	Evard Item no.
EVA.2020	CM centering vice	20	25	0.220	adapter flange	2020
EVA.2021	Inox CM centering vice	20	25	0.220	adapter flange	2021
EVA.5000	CM centering vice	50	89	2.3	adapter flange	5000
EVA.8000	CM centering vice	80	137	6.45	adapter flange	8000
EVA.1050	CM centering vice	105	178	15.5	adapter flange	1050





Combine the EA-91x rotary table with the CM 20 centering vice and split the  $\mu\text{'s}.$ 

### **Jaws**

	pL LEHMANN Item no.	Designation	Size [mm]	Weight [kg]	Required accessories	Evard Item no.
	EVA.500053	Standard jaw	50	Included in the weight of the vice	-	500053
20		Stepped jaw	50	Included in the weight of the vice	-	500051
5	EVA.500052	Claw jaw	50	Included in the weight of the vice	-	500052
	EVA.500055	Special claw jaw	50	Included in the weight of the vice	-	500055
	EVA.800053	Standard jaw	80	Included in the weight of the vice	-	800053
8		Stepped jaw	80	Included in the weight of the vice	-	800051
5	EVA.800052	Claw jaw	80	Included in the weight of the vice	-	800052
	EVA.800055	Special claw jaw	80	Included in the weight of the vice	-	800055
	EVA.105053	Standard jaw	105	Included in the weight of the vice	-	105053
105	EVA.105051	Stepped jaw	105	Included in the weight of the vice	-	105051
S	EVA.105052	Claw jaw	105	Included in the weight of the vice	-	105052
Ĭ	EVA.105055	Special claw jaw	105	Included in the weight of the vice	-	105055

### Adapter plate for CM 50 on Polymut

pL LEHMANN Item no.	Designation	Size of the CM [mm]	Size of the Polymut [mm]	Required accessories	Evard Item no.
EVA.500054	Adapter plate for CM 50 on Polymut 80	50	80	See Monoblock tower	500054
EVA.500057	Adapter plate for CM 50 on Polymut 50	50	50	See Monoblock tower	500057





Mounting chuck, automatic Type B  $\operatorname{\sf axfix}$ 

Further information: www.niederhauser.ch

Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation	System	axfix	Manual	Power-actuated	L [mm]	l 1 [mm]	12 [mm]	13 [mm]	D [mm]	d1 [mm]	d2 [mm]	d3 [mm]	Weight [kg]	max. speed [rpm]	For required options see p. 56/57	Niederhauser item no. incl. adapter flange
98	ZSP.510-B32Aka	Mounting chuck	B32	•		•	135	25	54.5	90	130	55	105				SPZ.91x-z3	510-B32KA
KK5	ZSP.520-B32Am	Mounting chuck	B32		•		149	59	75	-	130	53	62	88			SPI.91x-KK5	520-B32
호	ZSP.520-B45Am	Mounting chuck	B45		•		180	76	-	-	160	65	96	-			SPI.91x-KK5	520-B45

### Clamping capacity and passage

System	Clamping capacity [mm]	Collet passage [mm]			
B32	0.332	28			
B45	145	36			

### **Mounting chuck**









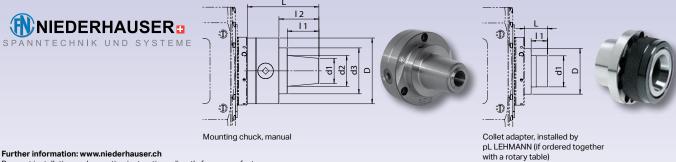






with standard B32 collet

System & iBox



Further information: www.niederhauser.ch Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation	System	Manual	Power-actuated	L [mm]	L1 [mm]	L2 [mm]	D [mm]	d1 [mm]	d2 [mm]	d3 [mm]	Weight [kg]	max. speed [rpm]	For required options see p. 56/57	Niederhauser item no. incl. adapter flange
	ZSP.520-W20Am	Mounting chuck	W20	•		127	36	53	130	40	54	88			SPI.91x-KK5	520-W20
KK5	ZSP.520-W25Am	Mounting chuck	W25	•		151	60	76	130	48	59	88			SPI.91x-KK5	520-W25
_	ZSP.520-W31Am	Mounting chuck	W31.75	•		138	48	64	130	53	62	88			SPI.91x-KK5	520-W31.75
	ZSP.91x-W20k	with HSK application	W20		•	39	15		130	47.5					SPZ.91x-z3	
88	ZSP.91x-W25k	with HSK application	W25		•	39	15		130	47.5					SPZ.91x-z3	
	ZSP.91x-W31k	with HSK application	W31.75		•	39	15		130	47.5					SPZ.91x-z3	

# Collet adapters (Type W) $\blacksquare$ LEHMANN $^{\circ}$







#### **Collet holder W25**





Radial run-out < 0.005 mm</li>

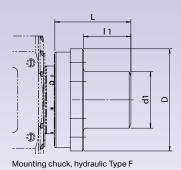
Rugged and slim design for better accessibility



Further information: www.ki-mech.ch Request installation and operating instructions directly from manufacturer

# Clamping capacity and (effective) passage

System	Clamping capacity [mm]	Collet passage [mm]	Standard effective passage [mm]
W20	0.323	14.5	14
W25	0.329	21	17
W31.75 (5C)	0.531	27	17



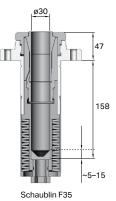
Further information: www.niederhauser.ch

Request installation and operating instructions directly from manufacturer

#### **Collet clamping Type F**

	pL LEHMANN Item no.	Designation	Manual	Pneumatic	Hydraulic	System	Clam- ping capacity [mm]	L [mm]	l 1 [mm]	D [mm]	d 1 [mm]	Weight [kg]	max. speed [rpm]	For required options see <b>p. 56/57</b>	Niederhauser item no. incl. adapter flange
d80	ZSP.510-F35Am	Mounting chuck	•			F35	130	129	40	160	90			SPI.91x-d80	510-F35
쁑	ZSP.510-F35Ak	Mount. chuck, power-actuated			•	F35	130	114.4	73.4	112	85			SPZ.91x-z9	510-F35K
KK5	ZSP.520-F48Am	Mounting chuck	•			F48	142	145	40	160	90			SPI.91x-KK5	520-F48
	ZSP.91x-F35k*	Collet adapter, power-actuated		•		F35	130							SPZ.91x-s9d30	

<sup>\*</sup> available with bar feed, see p. 57



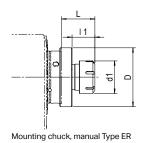


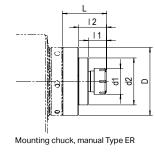


Clamping system

# **Collect clamping Type ER**

	pL LEHMANN Item no.	Designation	Manual	System	Clamping capacity [mm]	L [mm]	l 1 [mm]	12 [mm]	D [mm]	d1 [mm]	d2 [mm]	Weight [kg]	max. speed [rpm]	Niederhauser item no., incl. adapter flange
	ZSP.520-E25Am	Mounting chuck	•	ER-25	0.517	80	30	50	130	42	90			520-ER25
Ž Š	ZSP.520-E32Am	Mounting chuck	•	ER-32	122	88	38	50	130	50	90			520-ER32
	ZSP.520-E40Am	Mounting chuck	•	ER-40	230	90	40	50	130	63	90			520-ER40









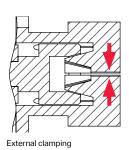


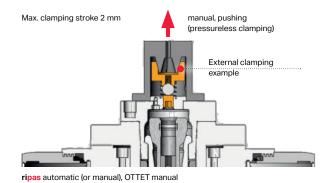
#### **OTTET** collet clamping

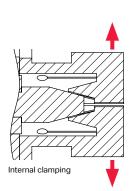
pL LEHMANN Item no.	Designation	Max. speed [rpm]	Required palletizing system ripas and clamping cylinder*
ZSP.91x-OTk	With HSK adapter, power-actuated		RIP.91x-63m-OT and SPZ.91x-s3 required
ZSP.91x-OTm	With HSK adapter, manual		RIP.91x-63p and SPZ.91x-z9 required

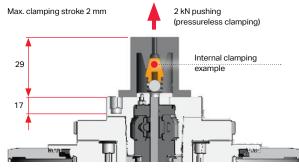
<sup>\*</sup> see p. 58/59

The collet chuck with clamping piston inside is suitable for internal and external clamping, pneumatically actuated.









ripas manual (automatic not possible), OTTET automatic





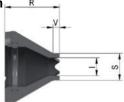
Further information: www.roehm.biz
Request installation and operating instructions directly from manufacturer

# Face driver, play-free version with hydraulic compensation for clockwise and counterclockwise rotation

	pL LEHMANN Item no.	Designation	Overhang [mm]	Max. workpiece weight [kg]	Max. axial load [kN]	Weight [kg]	Max. speed		RÖHM Item no., incl. adapter flange
d80	RÖH.510-SM	Face driver	65	100	20			SPI.91x-d80	1340450

#### Accessories: Driver plates / play-free / clockwise and counterclockwise rotation

	pL LEHMANN Item no.	Designation	S Clamping circle Ø	Associated center Ø	R Overhang [mm]	l [mm]	V [mm]	Weight [kg]	RÖHM Item no.
	RÖH.MS-DV08	Driver plate	8	4	38	4.5	4		1209000
eq	RÖH.MS-DV10	Driver plate	10	4	38	4.5	4		1209001
geared	RÖH.MS-DV12	Driver plate	12	6	36	7	4		1209002
<u>×</u>	RÖH.MS-DV16	Driver plate	16	10	33	11	4		1209003
directly	RÖH.MS-DV20	Driver plate	20	12	30	13	4		1209004
÷	RÖH.MS-DV25	Driver plate	25	16	30	17	8		1209005
	RÖH.MS-DV32	Driver plate	32	16	30	22	10		1209006
3.2	RÖH.MS-HM20	Driver plate	20	6	30	7	8		1209007
×	RÖH.MS-HM25	Driver plate	25	10	30	11	8		1209008
HM plates	RÖH.MS-HM32	Driver plate	32	16	30	17.5	10		1209009
M	RÖH.MS-HM40	Driver plate	40	16	30	27	16		1209010
	RÖH.MS-HM50	Driver plate	50	16	30	36			1209011
select.	RÖH.MS-HM63	Driver plate	63	16	30	49			1209012
3×	RÖH.MS-HM80	Driver plate	80	16	30	66			1209013



Driver plate, directly geared 1209000



Driver plate 3x select. HM plates 6 x 3.2 1209007

#### Accessories: Metal carbide driver plates, clockwise and counterclockwise rotation

pL LEHMANN Item no.	Designation	Clamping circle Ø	Size	Weight [kg]	RÖHM Item no.
RÖH.HMP-20	Metal carbide plate	20-32	6 x 3.2		88970
RÖH.HMP-40	Metal carbide plate	40–80	9.5 x 3.2		87931



metal curbule univer places sees

#### **Accessories: Center**

pL LEHMANN Item no.	Designation	Clamping circle Ø	Y Center Ø	N1 [mm]	Weight [kg]	RÖHM Item no.
RÖH.ZS-08	Center	8–10	4	90		1209016
RÖH.ZS-12	Center	12	6	90		1209017
RÖH.ZS-16	Center	16	10	90		1209018
RÖH.ZS-20	Center	20	12	90		1209019
RÖH.ZS-25	Center	25-80	16	90		1209020







**Further information: www.roehm.biz**Request installation and operating instructions directly from manufacturer

#### **Revolving centers**

	pL LEHMANN Item no.	Designation	Mount MK	Max.run-out deviation [mm]	Max. workpiece weight [kg]	Max. radial load [daN]	Max. speed [rpm]	D Moving-tip Ø [mm]	B Housing Ø [mm]	A [mm]	G [mm]	K [mm]	Weight [kg]	RÖHM Item no.
/ accessories	RÖH.ZS-DAMK3	with pressure display and length com- pensation; spring-loaded tip - spring travel max. 1.6 mm at axial clamping force of 550 daN; body hardened and ground – tip angle 60°	3	0.01	400	200	4000	25	64	105	23.8	31		60798
tions	RÖH.ZS-SAMK2	Standard version; body hardened and	2	0.005	200	100	7000	20	43	65	17.8	24		43115
do X	RÖH.ZS-SAMK3	and the second of the second o	3	0.005	400	200	6300	22	48.5	70.5	23.8	27		42315
<b>Failstock options</b>	RÖH.ZS-GDMK2 with small housing diameter, body harde-	2	0.005	200	100	7000	15	32	62	17.8	19.5		5336	
Īai	RÖH.ZS-GDMK3 ned and ground; tip angle 60°		3	0.005	400	200	7000	15	34	62	23.8	19.5		5429







Further information: www.piranha-clamp.ch

Request installation and operating instructions directly from manufacturer

#### Zero-point clamping plates on rotary table

	pL LEHMANN	<b>5</b>	Dimensions			Required spindle		PiranhaClamp item no.,
	Item no.	Designation	[mm]	[kg]	[rpm]	adapter	catalog reference	incl. HSK adapter
<u>e</u>		Flange 510	Ø 130 x 25			SPI.91x-d80	551159	551159
쁑		Zero point clamping plate Ø 130 mm	Ø 130 x 26			SPI.91x-d80	551161	551161

#### Zero point clamping plate to faceplates (axial discs) from p. 61

	pL LEHMANN		Dimensions	Weight	Max. speed	PiranhaClamp	PiranhaClamp
	Item no.	Designation	[mm]	[kg]	[rpm]	catalog reference	Item no.
d80		Zero-point clamping plate Butterfly to face plate (axial	170 x 170 x 26 Positioning pin Ø 40			540283	540283-510



EA-915 mit NSP

## Compatible centering vices

Article no.	Designation	Dimensions [mm]	Clamping capacity [mm]	Weight [kg]	Speed [rpm]
551112	PV75 clamping vice	75 x 56 x 55	19-49/25-55,0-31/5-35		
540362	Snapper 170 clamping vice	170 x 90 x 55	5-75/53-118		
540446	Snapper 170 clamping vice with higher jaws	170 x 90 x 65	5-75/53-118		
551076	Snapper 170 double station	170 x 90 x 55	2x 6-30 / 2x 26-52		
551075	Snapper 170 double station with higher jaws	170 x 90 x 65	2x 6 - 30 / 2x 26 - 52		
540444	Gepard 170 clamping vice, incl. aluminum jaws XS	170 x 90 x 85	0 – 155, varies with jaw type		
551079	Gepard 170 double station, incl. aluminum jaws XS	170 x 90 x 85	2 x 0 - 75		

#### **Ripas**

	pL LEHMANN Item no.	Designation	Manual	Clamping capacity	Centering vice length [mm]	Centering vice dimensions [mm]	Weight [kg]	max. speed [rpm]	PiranhaClamp Catalog Reference	PiranhaClamp Item no., incl. HSK adapter
		PV75, incl. flange	2)	19-49/25-55 0-31/5-35	75	75 x 56 x 55			551112	551112-63
88		Snapper 170, incl. flange	2)	5-75/53-18	170	170 x 90 x 55			540362	540362-63
		Gepard 170 with aluminum jaws XS, incl. flange	2)	0 – 155 varies with jaw type	170	170 x 90 x 84			540444	540444-63
		PV75, incl. flange	3)	19-49/25-55 0-31/5-35	75	75 x 56 x 55			551112	551112-63
		Snapper 170, incl. flange	3)	5-75/53-18	170	170 x 90 x 55			540362	540362-63
KK5		Gepard 170 with aluminum jaws XS, incl. flange	3)	0 – 155 varies with jaw type	170	170 x 90 x 84			540444	540444-63
		Snapper 300, incl. flange	3)	5-191/53-238	300	300 x 120 x 66			540401	540401-63
		Gepard 300 with aluminum jaws XS, incl. flange	3)	0 – 268 varies with jaw type	300	300 x 120 x 105			540400	540400-63

Additionally required clamping system (see **p. 59**) 2) = RIP.510-63m, 3) = RIP.520-63m

With some minor adjustment, all PiranhaClamp clamping devices can also be assembled to other zero-point clamping systems (Lang, Erowa, Schunk, AMF...).





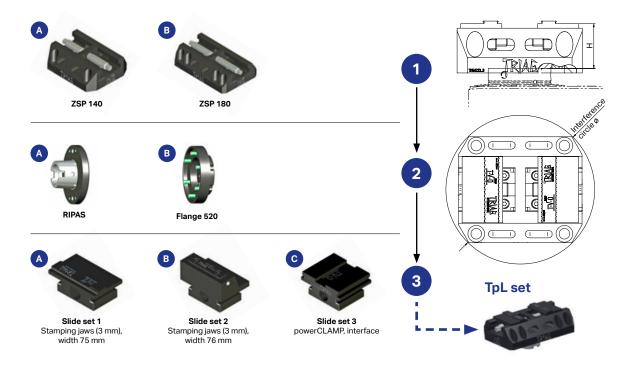






Gepard 300 Ripas





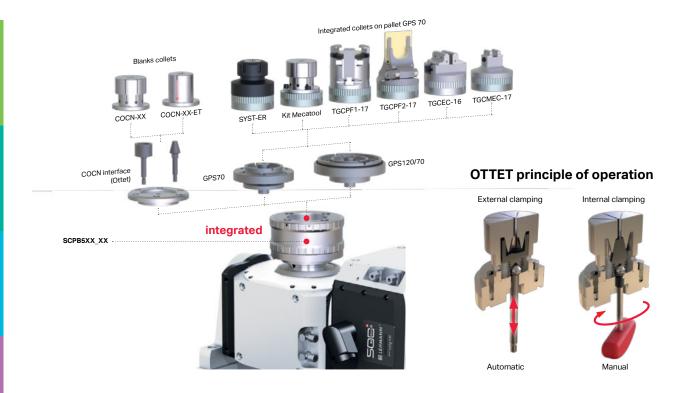
		1	2	3						
	L LEHMANN em no.	Centric clamping unit	Adapter	Stamping jaws	H [mm]	Interference circle ø [mm]	Weight, approx. [kg]	Max. Speed [rpm]	Required	IVO item no.
		700 4 40	4	A			4.8		RIP.91x-63x	26299-1-1-1
I۱	/O.5xx-140ada	ZSP 140 140 x 120 x 50		B		184	5.8		RIP.91x-63x	26299-1-1-2
ž E		140 X 120 X 00	adapter	0	50		5.6		RIP.91x-63x	26299-1-1-3
Ĭ		700 400	ada	A	50	216	6		RIP.91x-63x	26299-2-1-1
IV	/O.5xx-180ada	ZSP 180 180 x 120 x 50	oas	B			7		RIP.91x-63x	26299-2-1-2
		100 x 120 x 30	ripas	0			6.8		RIP.91x-63x	26299-2-1-3
				A			6.2			26299-1-4-1
I۱	/O.520-140fla	ZSP 140 140 x 120 x 50	0 x 50	B		184	7.2			26299-1-4-2
က		140 X 120 X 30		0	F2 F		7			26299-1-4-3
KK5			Flange	A	52.5		7.4			26299-2-4-1
I۱	/O.520-180fla	ZSP 180	Fla	B		216	8.4			26299-2-4-2
	18	180 x 120 x 50		0			8.2			26299-2-4-3

Further information: www.tgcolin.ch

GPS 120/70

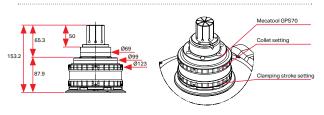
COCN interface, chuck 3R GPS 70 (image) or

Request installation and operating instructions directly from manufacturer

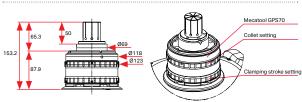


Following versions available for both EA and TAP9, versions «compact» on request

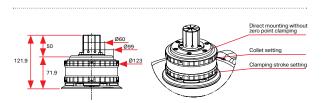
#### System 3R, GPS 70



### System 3R, GPS 70/120



#### **System OTTET (COCN)**



#### **Order items**

Item no. TGC.91x-G70	Designation Clamping device TG Colin, GPS 70, max. speed on request
TGC.91x-G12070	Clamping device TG Colin, GPS 120/70, max. speed on request
TGC.91x-COCN	Clamping device TG Colin, COCN, max. speed on request



Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

Further information: www.f-tool.com Request installation and operating instructions directly from manufacturer

	pL LEHMANN Item no.	Designation	Manual	D [mm]	L from spindle [mm]	Pallet sizes, max. [mm]	Workpiece weight (perm.) [kg]	Chuck weight (incl. adapter flange) [kg]	Weight [kg]	Max. speed [rpm]	Required spindle adapter	F-Tool Catalog Reference	F-Tool Item no., incl. adapter flange
	FTO.5xx-80P	Chuck 80 P	•	ø103	51	ø148	35	2.3		250	SPI.91x-d80	FT 01043	FT 02404
d80	FTO.5xx-50	Chuck 50	•	ø78	50	ø72	15	1.4		250	SPI.91x-d80	FT 02110	FT 02406
쁑	FTO.5xx-MC150P	Manual Chuck 150 P	•	ø150	55	ø148	50	4.3		250	SPI.91x-d80	FT 02443	On request
	FTO.5xx-PIN	PIN centering chuck	•	ø80	48	ø100	15	2.3		250	SPI.91x-d80	FT 01716	FT 02407



Chuck 80 P FT 01043



Chuck 50 FT 02110



Manual Chuck 150 P FT 02443



PIN centering chuck FT 01716

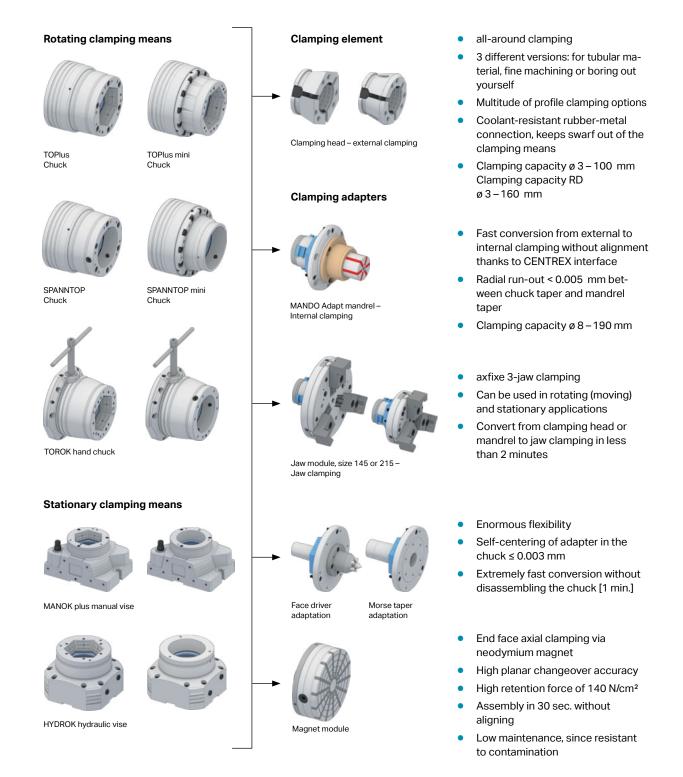
System & iBox

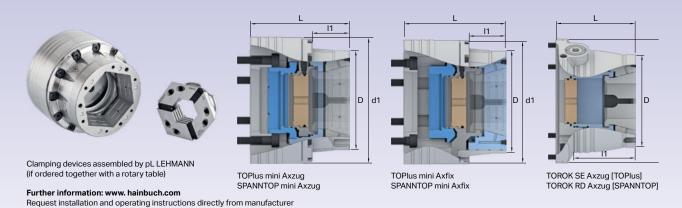


The clamping device serves as the starting point on the Lehmann CNC rotary table and can be be set up easily for your workpieces through use of a wide variety of clamping elements and adapters. Regardless of whether the clamping requires a round or profiled contour, whether unmachined or finish-machined parts are involved, whether soft or hard machining, or external or internal clamping – the HAINBUCH system offers a multitude of clamping options – without major expense or effort for setup.

#### Further information: www. hainbuch.com

Request installation and operating instructions directly from manufacturer





#### **HAINBUCH chucks TOPlus | TOROK**

	pL LEHMANN Item no.	Designation	Manual	Hydraulic	Size	Clamping capacity [mm]	L [mm]	l 1 [mm]	D [mm]	d 1 [mm]	Weight [kg]	Max. speed [rpm]	Required clamping cylinder	Compatible with modular system	HAINBUCH item no. incl. adapter flange
	HAI.510-tp-axz	TOPlus mini Axzug		•	52	452	103.5	42	119 f7	150			SPZ.91x-z9	•	10908/0002
88	HAI.510-tp-axf	TOPlus mini Axfix		•	52	452	104.5	44	119 f7	150			SPZ.91x-z9	•	10909/0002
	HAI.510-tp-to	TOROK SE Axzug	•		52	452	137	65.8	125 f7	174				•	10913/0001





TOPlus mini

#### **TOPlus**

- 25 % higher retention force than SPANNTOP
- Outstanding rigidity thanks to large contact surface of the clamping segments
- Insensitive to dirt thanks to clamping head geometry
- Lower centrifugal force losses compared to jaw chucks
- Optimal lubrication thanks to lubrication grooves in the clamping element holder
- Workpiece stabilized through axial pulling against workpiece stop
- Radial run-out < 0.015 mm
- Minimal interference contour and easy changing of the clamping heads

#### HAINBUCH chucks SPANNTOP | TOROK

	pL LEHMANN Item no.	Designation	Manual	Hydraulic	Size	Clam- ping capacity [mm]	L [mm]	l 1 [mm]	D [mm]	d 1 [mm]	Weight [kg]	max. speed [rpm]	Required clamping cylinder	Compatible with modular system	HAINBUCH Item no. incl. adapter flange
	HAI.510-st-axz	SPANNTOP mini Axzug		•	52	452	103.5	45	90 f7	150			SPZ.91x-z9	•	10910/0002
88	HAI.510-st-axf	SPANNTOP mini Axfix		•	52	452	104.5	44	98 f7	150			SPZ.91x-z9	•	10911/0002
J	HAI.510-st-to	TOROK RD Axzug	•		52	452	137	65.8	125 f7	174				•	10912/0001



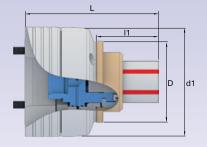
SPANNTOP mini

#### **SPANNTOP**

- Classical benefits of all HAINBUCH power chucks, e.g. high retention force, allaround clamping with high accuracy and exceptional ease of setup
- Lower centrifugal force losses compared to jaw chucks
- Workpiece stabilized through axial pulling against workpiece stop
- Radial run-out < 0.01 mm
- Minimal interference contour and easy changing of the clamping heads



MANDO T211 Axzug



MANDO T212 Axzug MANDO T812 Axfix

Clamping devices assembled by pL LEHMANN (if ordered together with a rotary table)

Further information: www. hainbuch.com

Request installation and operating instructions directly from manufacturer

#### **HAINBUCH clamping mandrels MANDO**

	pL LEHMANN Item no.	Designation	Hydraulic	Size	Clamping capacity [mm]	L [mm]	l 1 [mm]	D [mm]	d 1 [mm]	Weight [kg]	max. speed [rpm]	Required clam- ping cylinder	HAINBUCH Item no. incl. adapter flange
	HAI.510-ma-axz1	MANDO T212 Axzug	•	s	1621	112.5	47.5	70	141	7.60	5,450	SPZ.91x-z9	10915/0003
	HAI.510-ma-axf1	MANDO T812 Axfix	•	s	1621	117.5	49.5	70	141	7.90	5,450	SPZ.91x-z9	10916/0003
용	HAI.510-ma-axz2	MANDO T211 Axzug	•	0	2028	115.5	40.0	65	141	7.20	5,450	SPZ.91x-z9	10914/0001
Ĭ	HAI.510-ma-axz3	MANDO T212 Axzug	•	0	2028	123.5	58.5	90	141	8.10	5,450	SPZ.91x-z9	10915/0004
	HAI.510-ma-axf2	MANDO T812 Axfix	•	0	2028	129.5	60.5	90	141	8.50	5,450	SPZ.91x-z9	10916/0004



MANDO T211



MANDO T212 MANDO T812

#### **MANDO**

- Typical HAINBUCH features such as ease of setup, parallel clamping, optimal force transmission, high rigidity and retention force as well as low wear
- Workpiece stabilized through axial pulling against workpiece stop
- Radial run-out < 0.01 mm, version T812 < 0.025 mm
- Large adaptation range through use of vulcanized clamping elements
- Prepared for air system check at workpiece stop



SPANNTOP mini Axzug size 52 on TAP5



MANDO T211 size 0 on TAP9



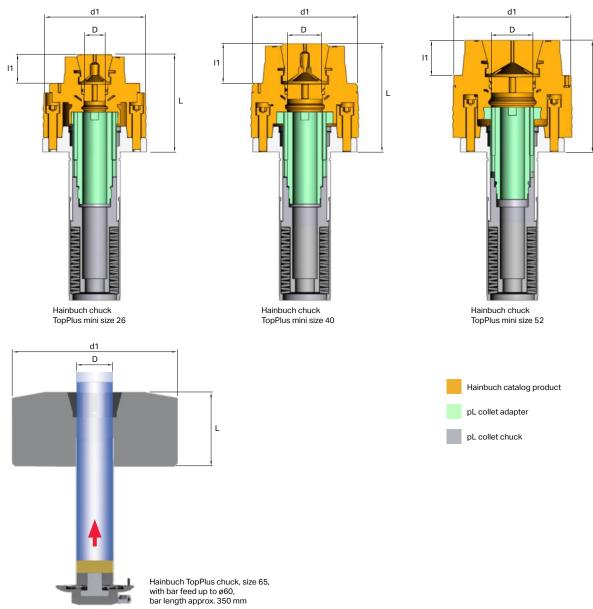
TOROK SE size 52 on TAP9



TOPlus mini Axfix size 52 on EA-915

pL LEHMANN Item no.	Designation	Pneumatic	Size	Clamping capacity [mm]	L [mm]	l 1 [mm]	D [mm]	d 1 [mm]	Weight [kg]	max. speed [rpm]	Required option	HAINBUCH Item no. incl. adapter flange
HAI.91x-tp26-axf**	TopPlus mini size 26	•	26	426	125	33	27	128	10,000	6.90	SPZ.91x-s9d30	
HAI.91x-tp40-axf**	TopPlus mini size 40	•	40	440	136	47	44	135	7,000	9.10	SPZ.91x-s9d30	
HAI.91x-tp52-axf**	TopPlus mini size 52	•	52	452	140	44	53	150	7,000	15.60	SPZ.91x-s9d30	
HAI.91x-tp65-axf*	TopPlus size 65	•	65	465	120		61	275			DDF.91x-04-HAI	

<sup>\*</sup> on request \*\* available with bar feed, see **p. 57** 





Further information: www.vb-tools.com

Request installation and operating instructions directly from manufacturer

#### SAFE and AirLine zero point clamping systems

	pL LEHMANN Item no.	Designation	Manual	open, pneumatic 6 bar	open, hydraulic 65 bar	D1 [mm]	D2 [mm]	L from spindle [mm]	Weight [kg]	Max. speed [rpm]	Draw-in force [kN]	Retention force [kN]	Required spindle adapter	Required rotary union*	vb Item no. incl. adapter flange
	VBO.510-al	AirLine		•		120	130	52			>9	40		DDF.91x-04-d80	755 510-04
88	VBO.510-SAh	SAFE20			•	120	130	50			>9	40		DDF.91x-04-d80	752 510-04
	VBO.510-SAm	SAFE20	•			120	130	50			>9	40	SPI.91x-d80		752 510-04-M

<sup>\*</sup> see p. 25, matching spindle adapter (p. 56) included in order item

#### Clamping means for SAFE and AirLine zero point clamping systems

	pL LEHMANN Item no.	Designation	Interference circle ø [mm]	L from support [mm]	Clamping capacity	Dimensions LxWxH	Weight [kg]	Max. speed [rpm]	vb Item no.
	VBO.al-76	AirLine vb centro76	175	75	5-74/44-120	Ø148x90x75			vb-centro76 AL
Center	VBO.al-76P	AirLine vb centro76 pendulum	175	75	22-74/62-120	Ø148x90x75			vb-centro76 P AL
Sen	VBO.sa-76	SAFE20 vb centro76	175	75	5-74/44-120	Ø148x90x75			vb-centro76 S
	VBO.sa-76P	SAFE20 vb centro76 pendulum	175	75	22-74/62-120	Ø148x90x75			vb-centro76 PS
	VBO.al-PalQ	AirLine Index pallet	206	35		150x150x35			755601 PL
pty	VBO.al-PalR	AirLine Index pallet. round	160	35		Ø160x35			755602 PL
Empty pallets	VBO.sa-PalQ	SAFE20 Index pallet	206	35		150x150x35			752601 PL
	VBO.sa-PalR	SAFE20 Index pallet, round	160	35		Ø160x35			752602 PL

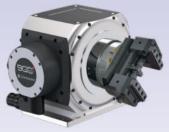
#### Center clamp on ripas or directly on spindle

	pL LEHMANN Item no.	Designation	Interference circle ø [mm]	L from support [mm]	Clamping capacity [mm]	Dimensions LXWXH [mm]	Weight [kg]	Max. speed [rpm]	vb Item no.
ripas	VBO.RIP-76	vb centro76, ripas	175	83	5-74/44-120	Ø148x90x83			vb-centro76 Ri
문	VBO.RIP-76P	vb centro76 pendulum, ripas	175	83	22-74/62-120	Ø148x90x83			vb-centro76 P Ri
08b	VBO.510-76	vb-centro76, direct	175	67	5-74/44-120	Ø148x90x75			vb-centro76 pL 510
쁑	VBO.510-76P	vb-centro76 pendulum, direct	175	67	22-74/62-120	Ø148x90x75			vb-centro76 P pL 510







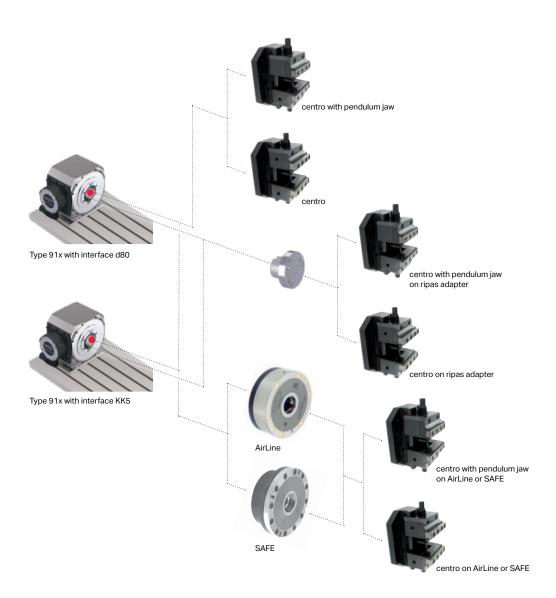


#### Further information: www.vb-tools.com

Request installation and operating instructions directly from manufacturer

## vb-centro76 jaw line

	vb Item no.	Designation	Dimension (LxWxH)	Weight [kg]	Speed [rpm]
Soft jaws	748-086ST	Soft steel jaws	86x60x40		
	748-086AL	Soft aluminum jaws	86x60x40		
Grip jaws	748-76-04-ST	Grip jaw, standard			
	748-76-04-RG	Grooved / Grip jaw			
	748-76-04-AL	Grip jaw for aluminum			
	748-76-04-L	Positive-fit jaws			
Accessories	748-76-M8	Workpiece stop			
	748-NM	Torque wrench			
	748-SW12	Wrench socket, 12 mm			

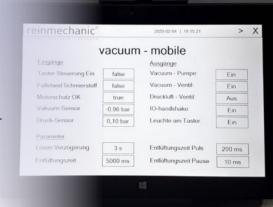


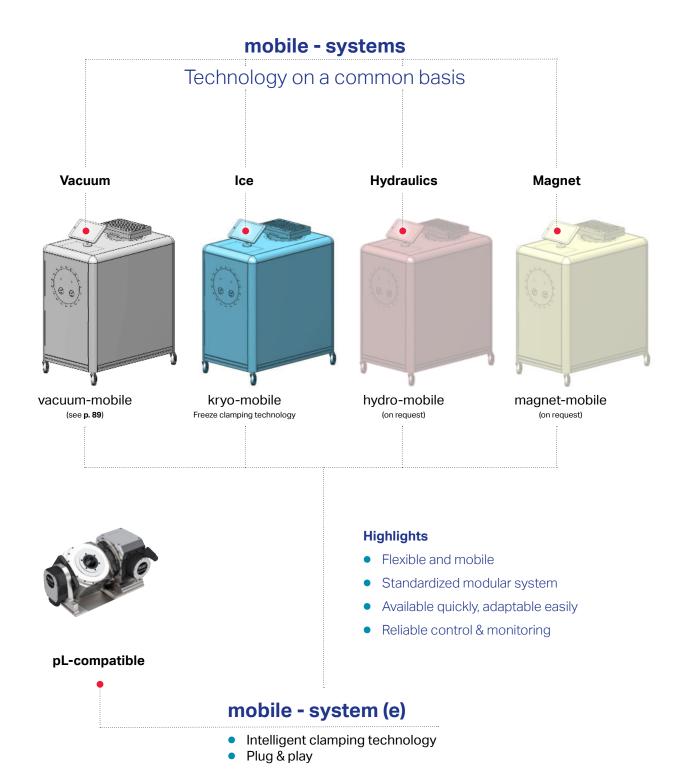


Control and monitor workpiece-dependent clamping technology using an integrated approach

Further information at: www.reinmechanic.de

Request installation and operating instructions directly from manufacturer





# reinmechanic Reinmechanic Reinmechanische Lösungen

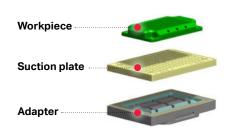
Vacuum clamping technology for mounting thin-walled workpieces, housings, plates ...

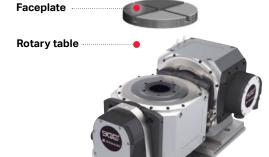
Further information at: www.reinmechanic.de

Request installation and operating instructions directly from manufacturer



# Example: vacuum - mobile Workpiece mount for rotary tables





pL rotary table T1-91x915 with reinmechanic-vacuum adapter and mechanical-universal suction plate

#### mobile-liquidSeparator

- Optional liquid separator
- Process-monitored
- Automatic feedback



#### mobile-systems available in three versions

#### «standard»

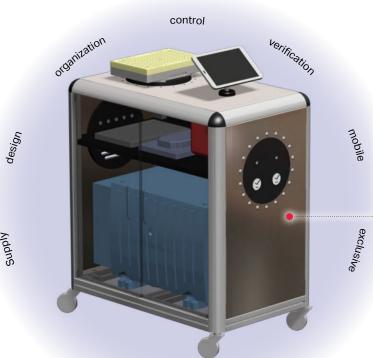
- Complete design
- Required functions
- Economical

#### «professional»

- Complete design
- Advanced functions
  - Semi-automated

#### Features of the reinmechanic-vacuum system:

- pl-compatible (ready to use)
- Production-oriented solution (manufacturing solutions)
- Individual sizing (lean production)
- reinmechanic adapter service (individual adapter service)
- Manufacturer-independent (all-round use)
- Industry 4.0 compatible
- Touchscreen control (easy handling)
- Self-monitoring overall system (self-monitoring)
- Command transfer to machine control (I/O handshake)



#### «premium»

- Complete design
- Industry 4.0-capable
- Touchscreen control

reinmechanic-vacuum-mobile «premium» with mechanical-vacuum adapter and mechanical-universal suction plate

Automation 4.0 - fully integrated



# Facts

# mobile - transferTool

#### handling «easy - in»

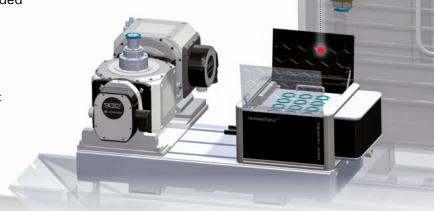
- Standardised gripper from Schunk (PGN+ xx)
- Easy handling via tool management
- Individual gripper jaws
- Control via internal cooling (beneficial with air)

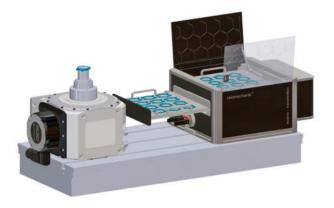
Ideal for miniature parts with dimensions of a few millimeters up to medium-sized workpieces with outside dimensions up to approx. 83 x 83 x 50 mm (depending on the interference contour of the plates, housing, bars)

# mobile - transferBox

Workpiece magazine directly where needed

- Storage area protected from chips
- Time-optimized provision
- Short transfer paths
- Configuration of individual, specific placement displays
- High reference accuracy
- Optional with workpiece cleaning function





#### **ROTOMATION** solution with

- Rotary table EA915 DD
- mobile transferBox (mtB)
- mobile partTablet (mpT)

More information: request our brochure ROTOMATION



# reinmechanic feinmechanische Lösungen

# mobile - control

# Control processes interactively

Various reinmechanic products can be fitted with an optional control system (mobile - control) for enhanced control, monitoring and management



# mobile-controlBox

 Fully integrated I/O Profinet solution for control



# mobile-processBox

- Communication with NC system
- Standard M-commands
- For installation in control cabinet
- Easy integration



# mobile controlTablet

For visualization and operation of the mobile-control software



### mobile - add-ons software modules

- mobile wireless
   WLAN / Bluetooth
- mobile data XML format; Windows-based
- mobile assist Intelligent and self-monitoring functions
- mobile service
   Remote maintenance and maintenance manager

- mobile mail Fault message and process message via e-mail
- mobile processing
   I/O Profinet for integrated automation
- mobile test
   Functions to test / simulate sequences
- mobile remoteVideo
   Video monitoring of you processes

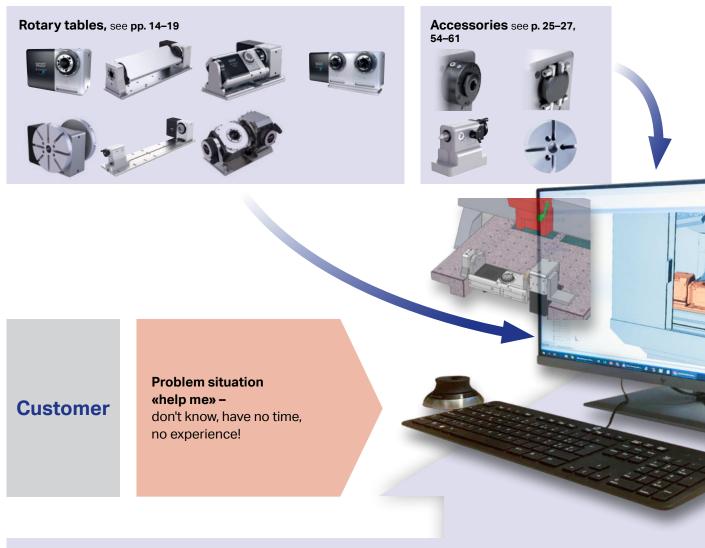
More information: request our brochure GO DIGITAL



**ROTOLUTION** – customer-specific turn-key solutions «ontop», largely with proven standard elements, from CAD to commissioning.

**ROTOMATION** – The ideal expansion with standardized automation. Economical. Professional. Simple.

#### **Standard**



































#### **ROTOLUTION**

## **CAD & adaptation**

- Installation check
- Adjustment to standard parts
- Special parts

#### **CAD & clamping means**

- Workpiece clamping
- Standard/special

see p. 62-87

\*Examples

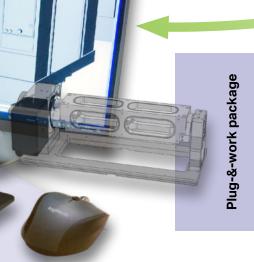
# ROTOMATION

#### **CAD & automation**

- Workpiece handling
- Partnerships (GU with partners) e.g. reinmechanic – mobile - concept

see **p. 88-91** 

Project management and execution, direct if needed



#### Problem solution «on top» –

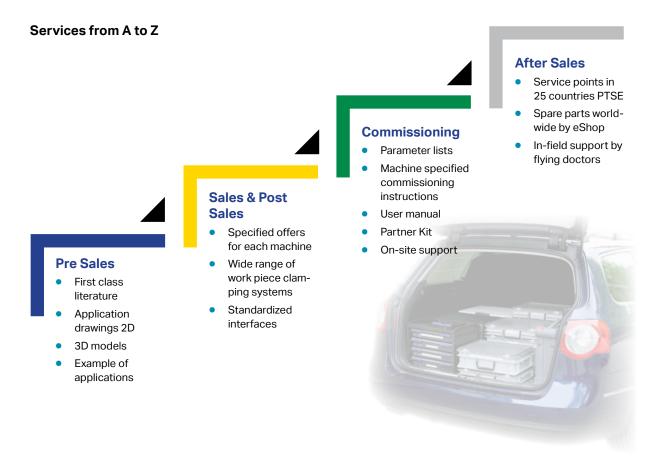
Standard and ROTOLUTION from a single source, ROTOMATION and machine in partnership

Customer



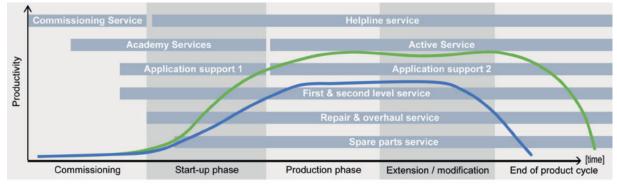






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